

THE OPTIMIZATION OF PIPE
DISTRIBUTION SYSTEMS

By

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A thesis submitted to the Faculty and the Board of Trustees of the Colorado School of Mines in partial fulfillment of the requirements for the degree of Master of Science (Mathematics).

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ABSTRACT

A systematic method is developed to determine the optimal pipe sizes for an irrigation pipe distribution system for the minimum total cost. A series of computer programs, based on dynamic and linear programming formulations, are used to produce the desired solution in a final report format. Two example problems are included to show the applications of the proposed algorithm.

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INTRODUCTION

The purpose of this thesis is to develop a systematic method of determining the optimal pipe sizes in a pipe distribution system for irrigation projects. Although this thesis will only deal with pipe networks for irrigation systems, the same principles could be modified for any pipe network designed to transport fluids.

There are basically two types of irrigation systems, pump and gravity. In a pump system, the total cost of pipe and the total cost of pumping must be minimized simultaneously to obtain the lowest combined total cost. In a gravity system, the beginning elevation of the water at the source is known, and the only objective is to minimize the total cost of pipe.

The two problems are similar in many aspects. For both types of systems, the geometric layout and the lengths of the pipe are known. Also, the hydraulic properties and costs of all the pipes to be considered are known or can be determined for each system. The purpose of a pipe distribution system for irrigation projects is to deliver to the farmer his desired flow of water at a required pressure. This point of delivery to the farmer will be referred to as a "delivery" in this thesis. For each system type, the required flow and pressure is known for each delivery. The only additional information needed for a pump system is the cost of power for pumping.

There have been several papers that have dealt with the problem of determining the economical pipe sizes for a pipe network. One of the earlier

articles was by Camp (1) who developed a mathematical relationship that expressed the total cost of the pipe distribution system as a function of pipe size. Camp did not present a practical method that would find the pipe sizes which would make this total cost a minimum for a practical or "real world" problem. For many years the design procedure for pipeline distribution systems was based on a trial and error method. For a given network, various combinations of pipe sizes were arrived at on the basis of personal judgment and the corresponding costs were computed. Then the total cost of the network was determined for each of the different combinations of pipe sizes, and the lowest cost system was selected. This approach was very time consuming, and most engineering organizations did not have a sufficient number of designers to thoroughly investigate the numerous combinations of pipe sizes. Often the time constraint on completing a job was such that only a few trials could be made. Obviously, there was always the probability that a more economical design existed.

A paper by Mandry (2) was published in 1967, and it described a practical procedure for solving the formulation proposed by Camp. Mandry presented a straight-forward approach for obtaining the solution for the problem, but his procedure was very tedious to use on a large distribution system.

Charles A. Calhoun (3) and Leo A. Kinney, Jr., worked for Mandry in the Canals and Pipelines Section of the Bureau of Reclamation until Mandry's death in 1966. Soon thereafter, Calhoun and Kinney developed computer programs to implement Mandry's method. These computer programs were limited to accommodate a single pipeline without any branches. However,

by making several computer runs, the minimum total cost could be obtained for a network with multiple branches.

The advent of the computer and operations research methods opened new doors for the designer of pipeline distribution systems. In 1968, Karmeli, Gadish, and Meyers (4) published an article on the formulation of the problem using linear programming and another article on solving the problem using dynamic programming. Calhoun's paper in 1970 presented a more detailed explanation of the linear programming formulation. Kally (6) and Liang (7) also had papers published describing dynamic programming formulations. Richard A. Simonds (8) and Kinney wrote a paper in 1972 which described the application of operations research techniques to optimize a pipe distribution system.

The two operations research methods mentioned earlier have been successfully used in the design of a pipe distribution system, but there were disadvantages in using them. Kinney developed a computer program using the dynamic programming philosophy to analyze an entire network in one run, but the output generated by this program was not in a final, usable format. Hillier and Lieberman (9) presented the following basic features which characterize a dynamic programming problem:

1. The problem can be divided into stages, with a policy decision required at each stage.
2. Each stage has a number of states associated with it.

3. The effect of the policy decision at each stage is to transform the current state into a state associated with the next stage.
4. Given the current state, an optimal policy for the remaining stages is independent of the policy adopted in previous stages.
5. The solution procedure begins by finding the optimal policy for each state of the last stage.
6. A recursive relationship is available which identifies the optimal policy for each state with n stages remaining, given the optimal policy for each state with $(n-1)$ stages remaining.
7. Using this recursive relationship, the solution procedure moves backward stage by stage each time finding the optimal policy for each state of that stage until it finds the optimal policy when starting at the initial stage.

The computer program generates one pipe diameter for each reach of pipe, which is the distance between deliveries. This was undesirable since on some reaches of pipe there would be excess pressure. What diameter and length of a smaller pipe size would eliminate this extra pressure? The designer knew the unknown length had to be a portion of the original length between deliveries, and in most situations the unknown pipe diameter would be the next smaller pipe size. Although these facts were beneficial in solving for the location that the pipe should change from one pipe diameter to the smaller pipe diameter, there would be numerous

computations for a large distribution system. The location of these pipe diameter changes are commonly known as taper locations or taper stations.

The results of the linear programming packages produced the taper locations, but additional problems arose. The linear programming formulation will be presented later in this thesis, and it will be shown that a group or series of pipe choices must be given for each reach of pipe. One method that is presently used in the preparation of data for a linear programming solution is to select for each reach one pipe size based on a velocity, say 5 feet per second. Using this pipe size as a base, the two next smaller and two next larger pipe diameters are selected, which would result in five different pipe sizes considered for each reach. The hydraulic properties of these pipe diameters are required for the constraint equations which will be formulated later in this thesis. The cost per foot of these pipes will be in the objective function which will also be later formulated. When the coefficients and right-hand sides of the objective function and constraint equations and inequalities are properly entered as input for a linear programming computer program, an optimal solution will be obtained.

This solution is only optimal with respect to the five pipe choices per reach which were under consideration without rigorous economical justification. If the five pipe diameters had been selected by some economical method, then the linear programming solution would be optimal in a broader sense.

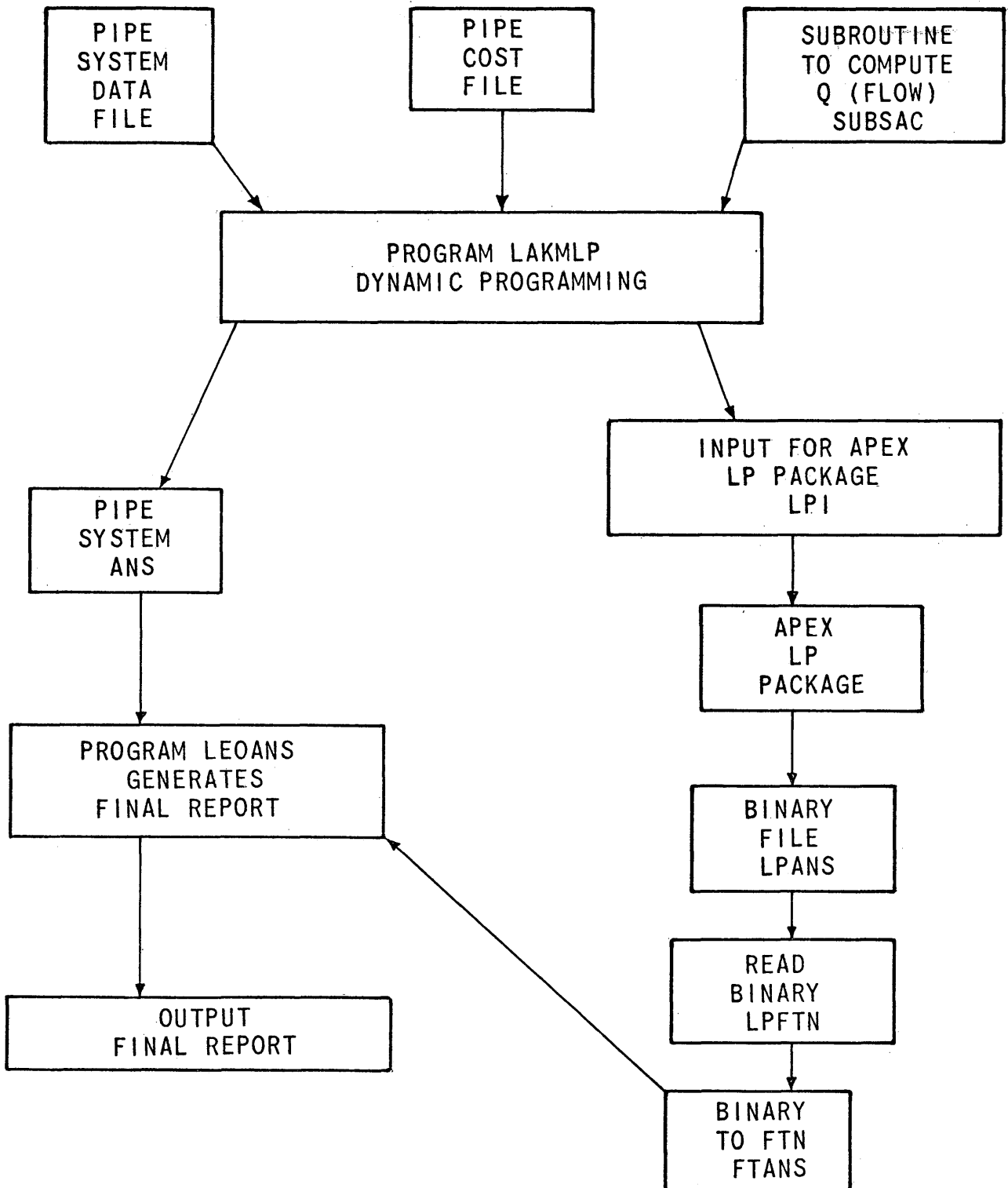
Another problem associated with using most linear programming computer programs is that the results generated are in tableau formats which are

cumbersome to use. The costs and hydraulic properties of the five pipe choices per reach are discrete parameters and are entered into the objective function and constraint equations as mentioned earlier. Therefore, the results in the final tableau have to be manually associated with the proper pipe diameter, which is a very tedious task for a large network.

A procedure will be shown in this thesis that uses the dynamic programming philosophy in conjunction with linear programming to produce computer output in report form that will not require any further adjustments before it is used. First will be presented the dynamic programming formulation for a pipe distribution system. Then, example problems will be solved using the dynamic programming computer program named LAKMLP. This is a program that was developed to solve a pipe distribution system using dynamic programming, and at the same time, automatically generate the input file for a linear programming package. Then will be developed the linear programming formulation for the same example problems. Next, a linear programming package will be used to generate a computer file that will be later required to develop the final report.

The flow diagram on page 7 indicates the input files, programs, and output files that will be used in this thesis. Program LAKMLP requires two input files: a pipe system file and a pipe cost file. The pipe system file contains general information about the pipe distribution system, such as the geometric layout and hydraulic requirements of the network. The cost per foot of the pipes are in the pipe cost file. Since the amount of water required for deliveries varies depending on the geographic location, a variable subroutine, SUBSAC, is needed to compute the flow or

FLOW DIAGRAM



cubic feet per second in the network. Program LAKMLP generates two output files which are named ANS and LP1. ANS contains information about the pipe system that is used at a later stage to generate the final report. The other output file, LP1, is the input file for the linear programming package APEX, which is available on the CDC 6400/6600 computer model CYBER 74-28. The file LP1 consists of the coefficients and the right-hand side of the objective function and the coefficients and the right-hand sides of the constraint equations and inequalities in an acceptable format for APEX.

The standard output from APEX is in tableau form and will not be used in this thesis. An individual familiar with linear programming could use the final tableau to perform a sensitivity analysis, but most designers who need to use this are not familiar with linear programming. Although it is usually advisable to perform a sensitivity analysis to determine the effect on the optimal solution if certain parameters take on other possible values, this will not be discussed in this thesis. An optional binary file, LPANS, is also generated by APEX. The program LPFTN was written to read this binary file and to create the fortran file FTANS. The pipe system file, ANS, and the file FTANS are input files for the computer program LEOANS. The program LEOANS is used to generate the final report. This procedure has been used successfully to solve a network that consisted of 325 reaches which produced an initial tableau with 976 rows and 1,951 columns for the linear programming model.

GRAVITY PROBLEM

The objective for a gravity pipe distribution system is to minimize only the total cost of pipe. Camp recognized that there is only one sequence of pipe diameters satisfying the length and hydraulic constraints that will yield the minimum total pipe cost.

Problem Description

Consider the pipe system and associated data as shown in figure 1.

In most gravity systems, the source of water is a canal with a known water surface elevation, such as Elevation 1100. Each point of delivery is indicated by an arrow in the figure. At each delivery, the number of acres to be irrigated and the required hydraulic elevation are known. The distances between the delivery points and/or sublaterals are also indicated.

Generally, the lines or laterals of a pipe distribution system are given names to facilitate the bookkeeping. The longest line is considered to be the main line, and in figure 1 was arbitrarily named Main. The lines that branch off of the main line are known as subs, and have also been named. If a line comes off of a sub, the name of this line implies this as SUB 1-A.

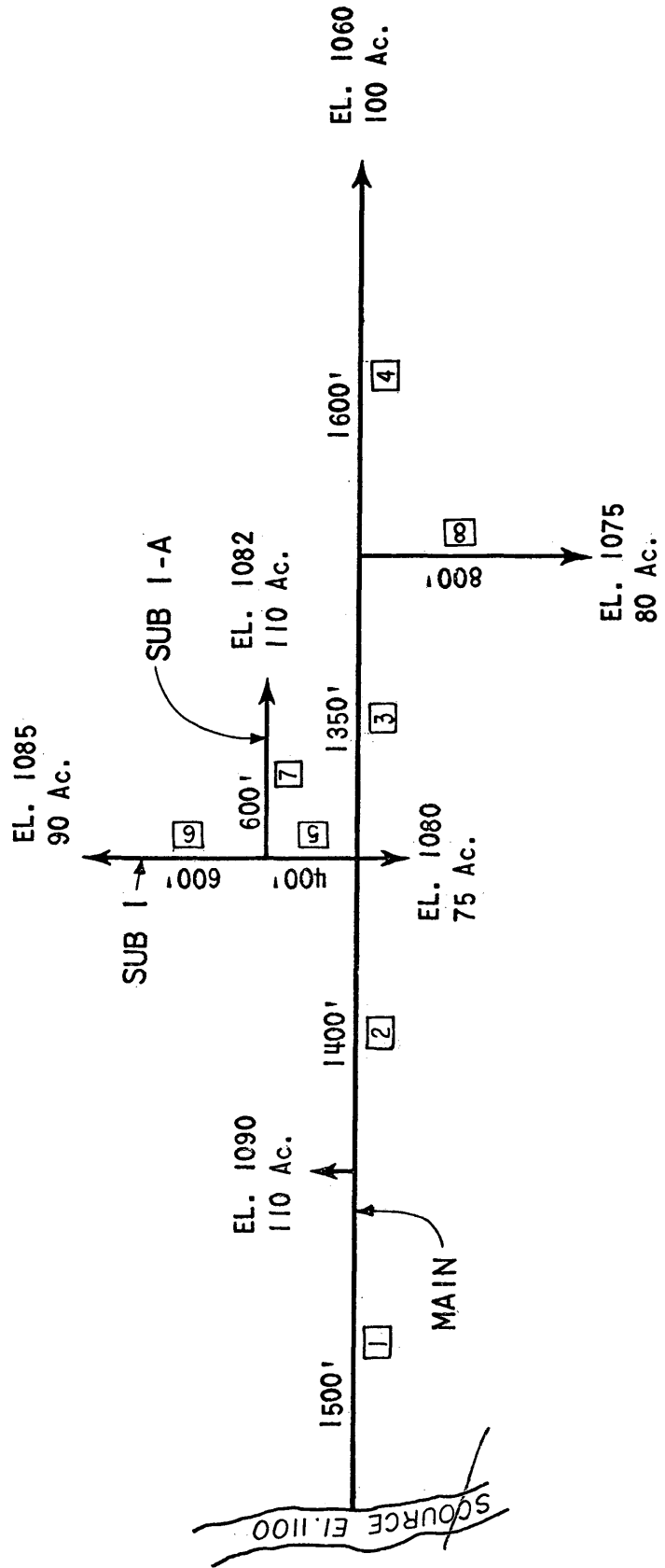


FIGURE 1

Dynamic Programming Formulation

Mandry developed a procedure to express the total cost of a pipe distribution system as a function of pipe size using Scobey's formula. The following formulation would have to be slightly modified if one of the other well-known pipe formulas was used in computing hydraulics for a pipe distribution system.

Scobey's pipe formula is:

$$Q = 3.72 C_s D^{2.625} H^{0.5} \quad (1)$$

where Q is flow in cubic feet per second; C_s is coefficient of friction; D is diameter of pipe in feet; and H is head loss in feet per 1,000 feet of pipe. This formula can be rewritten as:

$$D = \left(\frac{K Q^2 L}{h} \right)^{.19} \quad (2)$$

in which K is $1/(13,840 C_s^2)$; L is length of pipe reach; and h is the friction loss in the pipe reach. Mandry showed that the pipe costs can be expressed as:

$$C = y D^x \quad (3)$$

where C is installed cost in dollars per foot of pipe length; y is cost in dollars of 1 linear foot of 12-inch-diameter pipe; and x is the slope of the cost curve. The cost curve can be obtained by plotting the

cost per foot of pipe versus pipe diameter on log-log graph paper, and then values of x and y can be obtained as shown by Mandry. A least squares fit analysis could also be used to obtain the x and y values.

The total cost for the main line in figure 1 can be expressed as:

$$C = C_1 L_1 + C_2 L_2 + C_3 L_3 + C_4 L_4 \quad (4)$$

where the subscripts refer to the number of the pipe reach starting from the source. If $y D_i^x$ is substituted for C_i , $i = 1, 2, 3, 4$; the following expression is obtained:

$$C = y D_1^x L_1 + y D_2^x L_2 + y D_3^x L_3 + y D_4^x L_4 \quad (5)$$

Substituting $\left(\frac{K Q_i^2 L_i}{h_i} \right)^{.19}$ for D_i , $i = 1, 2, 3, 4$ results in:

$$C = Y \left(\frac{K Q_1^2 L_1}{h_1} \right)^{.19X} L_1 + Y \left(\frac{K Q_2^2 L_2}{h_2} \right)^{.19X} L_2 + Y \left(\frac{K Q_3^2 L_3}{h_3} \right)^{.19X} L_3 + Y \left(\frac{K Q_4^2 L_4}{h_4} \right)^{.19X} L_4$$

The cost of any two adjoining pipes in the network can be minimized by equating to zero the first derivative of C_i , cost per unit length, with respect to h_i , friction loss per unit length, in either pipe reach.

For the first two reaches, the first derivative with respect to h_1 is:

$$\frac{d (C_1 + C_2)}{d h_1} = 0 \quad (6)$$

Mandry noted that $d h_1 = -d h_2$ and, therefore, the minimum cost for the first two pipe reaches is:

$$\frac{d C_1}{d h_1} = \frac{d C_2}{d h_2} \quad (7)$$

and the minimum cost for the main line is:

$$\frac{d C_1}{d h_1} = \frac{d C_2}{d h_2} = \frac{d C_3}{d h_3} = \frac{d C_4}{d h_4} \quad (8)$$

where:

$$\frac{d C_1}{d h_1} = \frac{.19 \times K \cdot .19 X \cdot Q_1 \cdot .38 X \cdot L_1 \cdot 1 + .19 X}{h_1 \cdot 1 + .19 X} \quad (9)$$

$$\frac{d C_2}{d h_2} = \frac{.19 \times K \cdot .19 X \cdot Q_2 \cdot .38 X \cdot L_2 \cdot 1 + .19 X}{h_2 \cdot 1 + .19 X} \quad (10)$$

$$\frac{d C_3}{d h_3} = \frac{.19 \times K \cdot .19 X \cdot Q_3 \cdot .38 X \cdot L_3 \cdot 1 + .19 X}{h_3 \cdot 1 + .19 X} \quad (11)$$

$$\frac{d C_4}{d h_4} = \frac{.19 \times K \cdot .19 X \cdot Q_4 \cdot .38 X \cdot L_4 \cdot 1 + .19 X}{h_4 \cdot 1 + .19 X} \quad (12)$$

Let $S = \frac{h}{L}$, or

$$\frac{L_1}{h_1} \frac{1 + .19X}{1 + .19X} = \frac{1}{S_1} \frac{1}{1 + .19X} \quad (13)$$

By substituting expressions, collecting terms, and simplifying, equation (8) becomes:

$$\frac{Q_1 .38x}{S_1^1 + .19x} = \frac{Q_2 .38x}{S_2^1 + .19x} = \frac{Q_3 .38x}{S_3^1 + .19x} = \frac{Q_4 .38x}{S_4^1 + .19x} \quad (14)$$

Now, each of the slopes in equation (14) can be expressed as a function of S_1 .

$$S_2 = \left(\frac{Q_2 .38X}{Q_1 .38X} \right) \frac{1}{1 + .19X} S_1 \quad (15)$$

$$S_3 = \left(\frac{Q_3 .38X}{Q_1 .38X} \right) \frac{1}{1 + .19X} S_1 \quad (16)$$

$$S_4 = \left(\frac{Q_4 .38X}{Q_1 .38X} \right) \frac{1}{1 + .19X} S_1 \quad (17)$$

As Mandry noted, this information is interesting but useless in its present form. He was able to develop a series of equations for each reach of pipe. If the source of water is point zero, and the end of reach 1 is point 1, then the allowable friction loss from point zero to point one is the

difference in elevations of the two points. Let $h_{0,1}$ be this allowable friction loss. By subtracting the required elevations at each point from the elevation at the source, similar h 's can be obtained. Using the same method of subscripts for the L 's and Q 's, the following expressions can be obtained:

Reach 1:

$$S = \frac{h_{0,1}}{L_{0,1}}$$

Reach 2:

$$S = \frac{h_{0,2}}{L_{0,1} + \left(\frac{Q_{1,2}}{Q_{0,1}}\right) \frac{.38X}{1 + .19X} L_{1,2}}$$

Reach 3:

$$S = \frac{h_{0,3}}{L_{0,1} + \left(\frac{Q_{1,2}}{Q_{0,1}}\right) \frac{.38X}{1 + .19X} L_{1,2} + \left(\frac{Q_{2,3}}{Q_{0,1}}\right) \frac{.38X}{1 + .19X} L_{2,3}}$$

Reach 4:

$$S = \frac{h_{0,4}}{L_{0,1} + \left(\frac{Q_{1,2}}{Q_{0,1}}\right) \frac{.38X}{1 + .19X} L_{1,2} + \left(\frac{Q_{2,3}}{Q_{0,1}}\right) \frac{.38X}{1 + .19X} L_{2,3} + \left(\frac{Q_{3,4}}{Q_{0,1}}\right) \frac{.38X}{1 + .19X} L_{3,4}}$$

Similar equations can be developed for the reaches on the sublaterals.

Now the problem is to evaluate these equations, each of which will yield a different value for S . The reach with the minimum slope, S^* , is the economic control for all the pipe reaches upstream of that reach. The slopes of all the reaches down to the reach which had the minimum slope can now be determined by multiplying the minimum slope by the ratios of Q 's. For example, if the minimum slope had been found in reach 3, then the following economical slopes can be found by:

$$s_1 = \left(\frac{Q_{0,1}}{Q_{0,1}} \right) \frac{.38X}{1 + .19X} s^* = s^*$$

$$s_2 = \left(\frac{Q_{1,2}}{Q_{0,1}} \right) \frac{.38X}{1 + .19X} s^*$$

$$s_3 = \left(\frac{Q_{2,3}}{Q_{0,1}} \right) \frac{.38X}{1 + .19X} s^*$$

These economical slopes require nonstandard pipe diameters, and standard pipe diameters with slopes nearly matching these economical slopes must now be found. This completes the first stage of the dynamic programming problem. The source is now moved to the end of the reach that had the minimum slope. Then this procedure is repeated until the minimum slope is on the last reach of pipe. Thus the stages of the dynamic programming problem are not predetermined, but depend on the location of the minimum slope. The point at the end of this minimum slope is referred to as a control point. For a simple pipe system, with no sublaterals and only one control point at the end of the last reach, only one sequence of analysis is required. A large distribution system with many control points requires that this procedure be repeated as many times as the number of control points.

Problem Solution

The computer program LAKMLP was used to solve the problem described in figure 1. The appendix contains the listing of this program which was

written to solve a pipe distribution system using dynamic programming. The pipe prices and subroutine SACQ are also in the appendix.

The pipe prices are the total installed cost of the pipe. Included in this cost are excavation of pipe trench, furnishing and laying the pipe, and backfilling the trench. These costs vary with time and geographic location. Obtaining accurate pipe prices for a new pipe project might be the most difficult data to collect. Manufacturers of pipe are reluctant in giving out prices since they will be bidding for the pipe on the new project. However, the cost of pipe recently installed in the same vicinity gives an indication of what the pipe costs might be.

Subroutine SACQ was used to determine the flow for the pipe distribution system in figure 1. This is a variable subroutine and has to be modified for each new project, because water requirements for projects vary with types of crops and geographic location. The flow for the pipe distribution system in figure 1 is 6.1 gallons per minute per acre which is converted to cubic feet per second per acre in SACQ.

The pipe system file, DATA1, is in the appendix, and it contains information which describes the pipe system in figure 1. The first two lines contain the elevation at the source, pipe cost factors, x and y, and other miscellaneous information. The name of the main lateral is on the next line, and then there are five columns of numbers. The first column indicates if the lateral is the main or one of the subs. The next column is the station at which a reach of pipe begins. Stations are used in this file instead of lengths because surveyors stake pipe distribution

systems using the concept of stations. In the sixth column there is a number, -250., which denotes the value of an equation. An equation is often used by surveyors to join two lines together. The concepts of stations and equations are mentioned only to point out that the usual method of describing reaches of pipe does not have to be modified for the input file, DATA1. The third column denotes the number of acres to be irrigated, and the required elevations are in column four. The fifth column contains the natural ground elevations at each delivery and at each point that a sub begins.

The solution to this dynamic programming problem is in the appendix and has each lateral on a separate page. The name of the lateral is at the top of the page, and the pipe class design elevation is also indicated. This is the maximum pressure elevation that will occur on the pipes in the different reaches. This pressure is used in the design of the pipe and is called head class, which is denoted by HC in the last column. STATION and Q have been defined earlier. The hydraulic grade line is HGL and DIA is the pipe diameter in inches. V is the velocity and HV is the velocity head. The SLOPE, S, has been defined earlier, and LOSS was defined as h or the friction loss. AC is acres, and SAC is the summation of acres. The flow for each delivery is DQ, and the size of the delivery in inches is DEL. HGR is the required elevation, and NGS is the natural ground surface elevation. The value of the equation is denoted by EQ on lateral SUB2.

It should be noted at this point that the HGL is always greater than the required elevation, HGR. The dynamic programming formulation presented

earlier does not have the capability of determining more than one pipe size per reach. Linear programming does have this capability, and its formulation will be presented next.

Linear Programming Formulation

Using the format of Hillier and Lieberman, a linear programming problem is one which can be expressed as: minimize (or maximize) a linear function

$$Z = C_1 X_1 + C_2 X_2 + \dots + C_n X_n,$$

subject to the constraints,

$$a_{11} X_1 + a_{12} X_2 + \dots + a_{1n} X_n (\leq, =, \geq) b_1$$

$$a_{21} X_1 + a_{22} X_2 + \dots + a_{2n} X_n (\leq, =, \geq) b_2$$

$$a_{m1} X_1 + a_{m2} X_2 + \dots + a_{mn} X_n (\leq, =, \geq) b_m$$

and

$$X_1 \geq 0, X_2 \geq 0, \dots, X_n \geq 0$$

The objective function for a pipe distribution system should always be minimized, since the objective is to minimize the total cost for the system. For given sizes and types of pipe, the costs per foot of pipe (C_1, C_2, \dots, C_n) are known. The problem is to find the unknown lengths (X_1, X_2, \dots, X_n) of the various sizes of pipe which will minimize the objective function subject to the constraint equations and inequalities. For a pipe distribution system, there are three types of constraints. The length constraint requires that the summation of unknown lengths of various sizes of pipe equal the length of the reach under consideration. The hydraulic constraints are expressions relating the friction slopes and lengths of a pipe system to the allowable friction losses in the reaches. The third type of constraint requires that the values of the unknown lengths (X_1, X_2, \dots, X_n) be greater than or equal to zero. There are five variables and one each of the three types of constraints associated with each reach of pipe.

In the linear programming formulation for a pipe distribution system, a problem arises as to the proper choice of pipe diameters for each reach of pipe. The linear programming computer program will produce an optimal solution with respect to the pipe diameters and costs that are considered. The importance of obtaining accurate pipe costs has already been discussed in the dynamic programming formulation and is equally important in the linear programming formulation. To obtain the minimum total cost for a pipe distribution system, the choice of pipe sizes should be based on some type of economical analysis. The dynamic programming computer program presented earlier has already optimally selected one pipe diameter for each reach of pipe. To insure that the linear programming computer program

selects the optimal pipe diameters for each reach, five pipe diameters should be considered for each reach. Therefore, the pipe choices for each reach should consist of the pipe diameter selected by the dynamic programming computer program, the next two smaller pipe diameters, and the next two larger pipe diameters. It should be noted, that on most pipe distribution systems, there is a minimum pipe diameter that is allowed for any reach. The reasons for this limitation are varied, and will not be discussed in this thesis. This size limitation means that, for some reaches, the five pipe choices will be the smallest allowable five pipe diameters. For the distribution system shown in figure 1, the smallest allowable pipe diameter is a 6-inch-diameter pipe.

Using the data that are on figure 1 and the information that was generated by the program LAKMLP, the following two tables can be obtained:

TABLE I
DATA FOR PIPE SYSTEM IN FIGURE I

REACH NO.	LENGTH OF REACH IN FEET	FLOW, IN CUBIC FEET PER SECOND	ELEVATION REQUIRED, IN FEET
1	1500.	7.68	1090.
2	1400.	6.19	1080.
3	1350.	2.45	1071.
4	1600.	1.36	1060.
5	400.	2.72	1079.
6	600.	1.22	1085.
7	600.	1.50	1082.
8	800.	1.09	1075.

TABLE 2

POSSIBLE PIPE CHOICES

REACH	UNKNOWN VARIABLE	PIPE DIAMETER IN INCHES	FRICTION SLOPE IN FEET PER FOOT	COST, IN DOLLARS PER LINEAR FOOT
1	X ₁	27	.000443	19.10
	X ₂	24	.000823	16.38
	X ₃	21	.001907	13.70
	X ₄	18	.004285	10.45
	X ₅	15	.011158	8.31
2	X ₆	24	.000533	16.38
	X ₇	21	.001237	13.70
	X ₈	18	.002779	10.45
	X ₉	15	.007237	8.31
	X ₁₀	12	.023351	6.77
3	X ₁₁	15	.001133	8.31
	X ₁₂	12	.003655	6.77
	X ₁₃	10	.009518	5.73
	X ₁₄	8	.030712	4.65
	X ₁₅	6	.139071	3.65
4	X ₁₆	15	.000350	8.31
	X ₁₇	12	.001128	6.77
	X ₁₈	10	.002938	5.73
	X ₁₉	8	.009479	4.65
	X ₂₀	6	.042923	3.65
5	X ₂₁	18	.000537	10.45
	X ₂₂	15	.001398	8.31
	X ₂₃	12	.004512	6.77
	X ₂₄	10	.011750	5.73
	X ₂₅	8	.037916	4.65
6	X ₂₆	15	.000283	8.31
	X ₂₇	12	.000914	6.77
	X ₂₈	10	.002379	5.73
	X ₂₉	8	.007678	4.65
	X ₃₀	6	.034768	3.65
7	X ₃₁	15	.000423	8.31
	X ₃₂	12	.001365	6.77
	X ₃₃	10	.003554	5.73
	X ₃₄	8	.011470	4.65
	X ₃₅	6	.051937	3.65
8	X ₃₆	15	.000224	8.31
	X ₃₇	12	.000722	6.77
	X ₃₈	10	.001880	5.73
	X ₃₉	8	.006067	4.65
	X ₄₀	6	.027471	3.65

The objective function and constraint equations and inequalities can now be generated using the information in TABLES 1 and 2. The objective function would be:

$$\begin{aligned}
 Z = & 19.10 X_1 + 16.38 X_2 + 13.70 X_3 + 10.45 X_4 + 8.31 X_5 + \\
 & 16.38 X_6 + 13.70 X_7 + 10.45 X_8 + 8.31 X_9 + 6.77 X_{10} + \\
 & 8.31 X_{11} + 6.77 X_{12} + 5.73 X_{13} + 4.65 X_{14} + 3.65 X_{15} + \\
 & 8.31 X_{16} + 6.77 X_{17} + 5.73 X_{18} + 4.65 X_{19} + 3.65 X_{20} + \\
 & 10.45 X_{21} + 8.31 X_{22} + 6.77 X_{23} + 5.73 X_{24} + 4.65 X_{25} + \\
 & 8.31 X_{26} + 6.77 X_{27} + 5.73 X_{28} + 4.65 X_{29} + 3.65 X_{30} + \\
 & 8.31 X_{31} + 6.77 X_{32} + 5.73 X_{33} + 4.65 X_{34} + 3.65 X_{35} + \\
 & 8.31 X_{36} + 6.77 X_{37} + 5.73 X_{38} + 4.65 X_{39} + 3.65 X_{40}.
 \end{aligned}$$

The length constraints would be:

$$X_1 + X_2 + X_3 + X_4 + X_5 = 1,500.$$

$$X_6 + X_7 + X_8 + X_9 + X_{10} = 1,400.$$

$$X_{11} + X_{12} + X_{13} + X_{14} + X_{15} = 1,350.$$

$$X_{16} + X_{17} + X_{18} + X_{19} + X_{20} = 1,600.$$

$$X_{21} + X_{22} + X_{23} + X_{24} + X_{25} = 400.$$

$$X_{26} + X_{27} + X_{28} + X_{29} + X_{30} = 600.$$

$$X_{31} + X_{32} + X_{33} + X_{34} + X_{35} = 600.$$

$$X_{36} + X_{37} + X_{38} + X_{39} + X_{40} = 800.$$

The first hydraulic constraint would be:

$$1100. \quad .000443 X_1 \quad .000823 X_2 \quad .001907 X_3 - .004285 X_4 \quad .011158 X_5 \geq 1,090.$$

This constraint may be written as:

$$.000443 X_1 + .00823 X_2 + .001907 X_3 + .004285 X_4 + .01158 X_5 \leq 10.$$

Similarly, the other hydraulic constraints are as follows:

to the second reach

$$.000443 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 +$$

$$.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} \leq 20.$$

to the third reach

$$\begin{aligned}
 &.000443 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 + \\
 &.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} + \\
 &.001133 X_{11} + .003655 X_{12} + .009518 X_{13} + .030712 X_{14} + .139071 X_{15} \leq 29.
 \end{aligned}$$

to the fourth reach

$$\begin{aligned}
 &.000433 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 + \\
 &.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} + \\
 &.001133 X_{11} + .003655 X_{12} + .009518 X_{13} + .030712 X_{14} + .139071 X_{15} + \\
 &.000350 X_{16} + .001128 X_{17} + .002938 X_{18} + .009479 X_{19} + .042923 X_{20} \leq 40.
 \end{aligned}$$

to the fifth reach

$$\begin{aligned}
 &.000433 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 + \\
 &.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} + \\
 &.000537 X_{21} + .001398 X_{22} + .004512 X_{23} + .011750 X_{24} + .037916 X_{25} \leq 21.
 \end{aligned}$$

to the sixth reach

$$\begin{aligned}
 &.000433 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 + \\
 &.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} +
 \end{aligned}$$

$$.00537 X_{21} + .001398 X_{22} + .004512 X_{23} + .011750 X_{24} + .037916 X_{25} +$$

$$.000283 X_{26} + .000914 X_{27} + .002379 X_{28} + .007678 X_{29} + .034768 X_{30} \leq 13.5.$$

to the seventh reach

$$.000433 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 +$$

$$.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} +$$

$$.000537 X_{21} + .001398 X_{22} + .004512 X_{23} + .011750 X_{24} + .037916 X_{25} +$$

$$.000423 X_{31} + .001365 X_{32} + .003554 X_{33} + .011470 X_{34} + .051937 X_{35} \leq 15.$$

to the eighth reach

$$.000433 X_1 + .000823 X_2 + .001907 X_3 + .004285 X_4 + .011158 X_5 +$$

$$.000533 X_6 + .001237 X_7 + .002779 X_8 + .007237 X_9 + .023351 X_{10} +$$

$$.001133 X_{11} + .003655 X_{12} + .009518 X_{13} + .030712 X_{14} + .139071 X_{15} +$$

$$.000224 X_{36} + .000722 X_{37} + .001880 X_{38} + .006067 X_{39} + .027471 X_{40} \leq 23.5.$$

The hydraulic constraints that contain the reaches in the subs have 1.5 feet subtracted from the right-hand sides. This is to compensate for the tee loss and valve loss that is at the beginning of the sub. Most subs are connected to the main lateral or another sub by means of a

tee. A hydraulic loss occurs when the water changes direction to go to the sub. Since the pipe sizes are unknown, the tee loss and valve loss cannot be computed at this time, but are estimated to be 1.5 feet. Experience shows this to be an adequate approximation for this type problem. Also, the unknown variables X_i , $i = 1$ to 40, must be greater than or equal to zero.

Problem Solution

Formulating the objective function and the constraint equations and inequalities for the eight reaches of the pipe distribution system in figure 1 might be considered a fairly easy task, but the formulation of a large distribution system with hundreds of reaches would be very cumbersome. After the dynamic programming solution for a pipe distribution is obtained, program LAKMLP generates the linear programming formulation for the problem and creates a data file, LP1. This data file is the input file for the linear programming routine APEX, which is available on the Control Data Corporation 6400/6600 computer, model CYBER 74-28. Most of the computer manufacturers have linear programming routines available as software accessories to their computers. Since APEX was readily accessible, it was used in solving this linear programming problem.

The APEX routine has a number of optional forms in which the output may appear. The form of output that was selected is a binary file, LPANS, with the answers printed in a format that can be easily read by another computer program. The program LPFTN, which is listed in the appendix, was written to read this binary file and create another file, FTANS.

FTANS contains the value of the objective function and the values of each of the unknown variables. At the time the program LAKMLP executed, it created a file, ANS, which contains the geometric layout and properties of the pipe distribution system in figure 1.

Program LEOANS also appears in the appendix and was written to read the two files FTANS and ANS, and then generate output in a final report format.

This final report is in the appendix and in many ways is similar to the output that was generated by the dynamic programming solution. However, there are some differences such as the additional two stations 3671.11 and 5665.00 on the Main lateral. These are known as taper stations, since two pipe diameters were chosen for a single reach between the two original stations.

On each lateral there is at least one HGL that is equal the corresponding HGR at the same station. These occurrences have been underlined to emphasize that these two are equal. At the beginning of each sub, the loss for the velocity head, tee loss, and valve loss have been subtracted.

These final report sheets are as the name implies, and require no further manipulation except for some special cases. The adjustments for any special problem that arises could be manually accomplished with very little effort.

The total cost of pipe for the pipe distribution system shown in figure 1 is the last printed line on the sheet titled SUB2. This total cost was obtained from the linear programming solution, and is the value of the objective function.

PUMP PROBLEM

The total cost of pipe and the cost of pumping must be minimized simultaneously to obtain the minimum total cost of a pumped pipe distribution system. In other words, the pump problem is the same as the gravity problem with the addition of a term describing the total pump cost.

Problem Description

Consider the pipe system and associated data as shown in figure 2. The pump pipe distribution system resembles the gravity system with the exception of the pumping plant and tank. The pumping plant is required to pump water into the tank at sufficient elevation to serve all of the deliveries. Now the problem is to solve for this elevation and at the same time minimize the cost of pumping and the total cost of pipe.

Dynamic Programming Formulation

Mandry developed an expression that relates the cost of pumping and the cost of pipe to the pipe diameter. He took the partial derivative of the present worth to find the economical pipe diameter, as follows:

$$W = a_n N \Psi \phi Q \frac{Kq^2}{D^{5.25}} + yD^x \quad (18)$$

where: W = present worth

a_n = present worth factor based on some number of years at a
specified interest rate

- N = number of kilowatt-hours of energy necessary to lift
 1 cubic foot per second 1 foot
 Ψ = equivalent number of peak periods per year
 ϕ = cost of power in mills per kilowatt-hour
 $K = 1/(13,840Cs^2)$ based on Scobey's formula
 Q = total flow in cubic feet per second that is to be pumped
 q = flow in a particular reach
 x = slope of the pipe cost curve
 y = cost of 1 linear foot of 12-inch-diameter pipe
 D = pipe diameter in feet

For any particular pipe distribution system, $C = a_n N \Psi \phi Q K q^2$ is a constant.

Then,

$$W = CD^{-5.25} + yD^x \quad (19)$$

Taking the partial derivative of present worth, W , with respect to D results in:

$$\frac{\partial W}{\partial D} = -5.25 C D^{-6.25} + x y D^{x-1} \quad (20)$$

Setting $\frac{\partial W}{\partial D} = 0$, for minimum present worth yields

$$5.25 C D^{-6.25} = x y D^{x-1} \quad (21)$$

$$5.25 C = x y D^{x+5.25}$$

and

$$D \text{ (economical)} = \left(\frac{5.25 C}{x y} \right)^{\frac{1}{x + 5.25}} \quad (22)$$

Beveridge and Schechter (10) presented another method, geometric programming, to obtain this relationship.

$$\text{Min } W(D) = C D^{-5.25} + y D^x \quad (23)$$

$$\delta_1 + \delta_2 = 1$$

$$(D) \quad -5.25 \delta_1 + x \delta_2 = 0$$

$$-5.25 (1 - \delta_2) + x \delta_2 = 0$$

$$-5.25 + 5.25 \delta_2 + x \delta_2 = 0$$

$$\delta_2 (5.25 + x) = 5.25$$

$$\delta_2 = \frac{5.25}{5.25 + x}$$

$$\delta_1 = 1 - \frac{5.25}{5.25 + x} = \frac{x}{5.25 + x}$$

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This predual at optimality is:

$$\frac{C D^{-5.25}}{x} = \frac{y D^x}{5.25} \quad (24)$$

$$D^x + 5.25 = \frac{5.25 C}{x y}$$

$$D \text{ (economical)} = \left(\frac{5.25 C}{x y} \right)^{\frac{1}{x + 5.25}} \quad (25)$$

This expression for the economical pipe diameter is the same as obtained earlier in equation (22).

The geometric programming solution was presented at this time to provide some additional valuable information. For the pipe distribution system in figure 2, say that $x = 1.53$.

Then,

$$\delta_1 = \frac{x}{5.25 + x} = .23$$

$$\delta_2 = \frac{5.25}{5.25 + x} = .77$$

This means that the term $C D^{-5.25}$, the cost of pumping, should be 23 percent of the total cost, and the term $y D^x$, the cost of pipe, should be 77 percent of the total cost of the pipe distribution system. These percentages are for an optimal design for a pumped pipe distribution system, and comparisons of the actual cost for pumping and pipe should be made after the project has been constructed.

Now, to determine the unknown water surface in the tank, the formula for the economical pipe must be used in a systematic manner. For each of

the reaches, the pipe diameter can be determined by the formula that was derived earlier, since for a specific project, the formula

$$D \text{ (economical)} = \left(\frac{5.25 C}{x y} \right)^{\frac{1}{x + 5.25}}$$

has only the pipe diameter unknown.

First the pipe diameter in the last reach of the main is computed. Then the friction loss is calculated for this reach using Scobey's formula. Next, the hydraulic grade line for the beginning of the reach is obtained by adding the friction loss to the elevation required at the end of the reach. This procedure is repeated until a junction point is reached where a sublateral joins the main line. Then the same procedure that was used on the main to obtain the hydraulic grade line at this junction should be applied to the sublateral. Next, the hydraulic grade line computed on the sub is compared to the hydraulic grade line on the main. The larger of these two hydraulic grade lines is then selected at the next starting point and the process continues until the tank is reached. At that point, the last hydraulic grade line found is the required water surface in the tank.

This method proposed by Mandry, proceeds through a pipe network until the tank water surface has been obtained, but in doing so, has not economically sized the pipe on the reaches that had the smaller hydraulic grade lines. But after the water surface in the tank has been established, the pump problem becomes a gravity problem with a known water surface equal

to the water surface elevation in the tank. Then the gravity formulation for dynamic programming presented earlier in this thesis can be applied to the problem.

Problem Solution

The pumped pipe distribution problem in figure 2 was solved using the computer program LAKMLP. In Mandry's paper, the determination of the various pumping cost factors was presented and will not be reproduced in this thesis. The following values were used to obtain the solution for the example problem in figure 2:

$$\begin{array}{ll} x = 1.53 & \Psi = 2.3675 \\ y = 7.1 & \phi = 0.006 \\ N = 45.0 & a_n = 30.525 \end{array}$$

The data file, DATA2, for the pumped pipe problem is in the appendix.

The pumped problem solution also appears in the appendix and is very similar in appearance to the solution for the gravity problem. The major difference is the tank water surface E1. 231 which is printed near the top of the main line page. The remaining headings and symbols have the same meanings as for the gravity problem.

Linear Programming Formulation

Once the tank water surface elevation is known for a pumped pipe distribution system, determining the pipe sizes to obtain the minimum total pipe cost becomes a gravity problem. Since the linear programming formulation for a gravity problem has been presented earlier in this thesis, it will not be repeated.

Problem Solution

Program LAKMLP was used to determine the tank water surface elevation 231.00 for the pumped pipe distribution system in figure 2. As was done earlier for the gravity problem, program LAKMLP generated the input file for the linear programming package APEX. The binary file created by APEX was read by the program LPFTN, which produced the file FTANS. The file ANS created earlier by LAKMLP and the file FTANS were used as input files by the program LEOANS to generate the final report.

The final report for the pumped pipe distribution system is in the appendix, and is very similar to the final report for the gravity distribution system. The Main Lateral is printed first and the tank water surface is near the top of the page. Taper stations were computed between stations 200 and 2000 and between stations 4900 and 6300. It is interesting to note that on Sublateral B there is not an HGL (hydraulic grade line) that is equal to an HGR (required elevation). This is because Sublateral B-1 requires a higher hydraulic grade line at station 1000, and the minimum allowable

pipe size of 6 inches was placed in the last reach of Sublateral B. This output is in final form, except for special cases, and does not require any further modifications.

CONCLUSION

It has been shown that the optimal pipe sizes for two types of pipe distribution systems can be obtained and printed in a final report format. This final report is usable to those familiar with civil engineering terminology, but unfamiliar with linear programming and dynamic programming techniques, and overcomes the major obstacle to the use of those techniques. Using a dynamic programming computer program to generate the input file for a linear programming package is a new concept, and should be considered in obtaining the solution to other optimization problems.

The design of other types of pipe systems, such as "loop" systems, requires modifying the techniques described in this thesis. A loop system, as the name implies, is a pipe network which consists of piping that permits the water to flow in more than one direction. Normally, these loop systems are not encountered in irrigation pipe distribution systems, but are often found in municipal water networks. A problem of this type has been optimized with a revised version of the techniques presented in this thesis.

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**** PROGRAM LAKMLP ****

```

6 TELOS2(93),TELOS3(180),TELOS4(150),TELOS5(50),
6 IVALV2(93),IVALV3(180),IVALV4(150),IVALV5(50)

```

```

REAL L1,L2,L3,L4,L5
INTEGER SENTRY

```

```
CALL DATE(TODAY)
```

```
WRITE (6,1)
```

```
1 FORMAT (1H1)
```

```
IMAX=36
```

```
JMAX=93
```

```
KMAX=180
```

```
LMAX=150
```

```
MMAX=50
```

```
PI=3.14159
```

```
JW=2
```

```
10 READ (5,20) TEELOS,PIPCOV,DWSADD,X,Y,CSS,CSB,PIPMIN,ITAP
```

```
20 FORMAT (2F5.2,6F10.2,I10)
```

```
C
```

```
TEELOS - TEE LOSS FOR SUB - IF BLANK,TEELOS=2.0
```

```
C
```

```
PIPCOV - AVE. EARTH COVER OVER PIPE
```

```
C
```

```
DWSADD - AMOUNT TO ADD TO OBTAIN DESIRED DELIVERY WATER SURFACE
```

```
C
```

```
X AND Y - PIPE COST FACTORS
```

```
C
```

```
CSS - SCOBEE CS FOR SMALL PIPE (LESS THAN 23 INCHES)
```

```
C
```

```
CSB - SCOBEE CS FOR BIG PIPE (GREATER THAN 23 INCHES)
```

```
C
```

```
PIPMIN - MINIMUM PIPE SIZE - USUALLY 4-INCH
```

```
C
```

```
IF (ITAP.NE.0) JW=6
```

```
K2 = 0
```

```
K3 = 0
```

```
K4 = 0
```

```
K5 = 0
```

```
ND=0
```

```
NN=0
```

```
SJEXC=0.
```

```
SJBKF=0.
```

```
IF (TEELOS.NE.0.0) GO TO 30
```

```
TEELOS=2.0
```

```
30 READ (5,40) MDEL,SENTRY,ITYPE,TQP,CP,AVH1,HVH1,TKWSEL,GOIFF,INPUT
```

```
40 FORMAT (2I5,I10,5F10.2,F5.2,I5)
```

```
C
```

```
MDEL - 1 TO READ IN DELIVERY SIZE - OTHERWISE BLANK OR 7990
```

```
C
```

```
SENTRY - 9 TO START JOB OR LATERAL -- 3 TO COMPUTE QUANTITIES
```

```
C
```

```
ITYPE - TYPE OF SYSTEM
```

```
C
```

```
1 - GRAVITY FROM CANAL
```

```
C
```

```
2 - PUMP INTO ELEVATED TANK NEAR PUMPING PLANT
```

```
C
```

```
3 - PUMP INTO RES. OR REG. TANK WITH KNOWN WATER SURFACE
```

```
C
```

```
4 - PUMP INTO RES. OR REG. TANK WITH UNKNOWN WATER SURFACE
```

```
C
```

```
TQP - TOTAL Q FOR EACH LATERAL SYSTEM
```

```
C
```

```
CP - PUMP FACTOR
```

**** PROGRAM LAKMLP ****

C AVH1 - AVAILABLE HEAD FOR MAIN LATERAL
 C HVH1 - MAXIMUM ELEVATION FOR PIPE CLASS WITHOUT WATERHAMMER
 C TKWSEL - KNOWN WATER SURFACE IN AFTERBAY TANK OR RESERVOIR
 C GDIFF - GRAVITY DIFFERENCE - IF BLANK,GDIFF=1.0
 C INPUT - 1-FOR INTERMEDIATE PUMP CONTROLS BLANK OR 0 FOR NONE
 C

WRITE (6,1)

ZP=1.7/(X+5.25)

ZG=0.38*X/(1.+0.19*X)

LASAV=0

ICOUNT=1

JCOUNT=0

KCOUNT=0

J=0

JJ=1

K=0

KK=0

L=0

LL=0

M=0

MM=0

IG=0

IF (SENTRY.NE.9 .AND. SENTRY.NE.8) GO TO 9999

IF (SENTRY.EQ.8) GO TO 9999

IF (CP.NE. 0.0) GO TO 50

CP=.43

50 QD=(TQP**ZP)*CP*12.

IF (GDIFF.NE.0.0) GO TO 1000

GDIFF=1.0

C

C

READ IN MAIN LATERAL

C

SPACES 2 THROUGH 30

C

1000 READ (5,1010) (LAT1(II),II=1,3),IDUM

1010 FORMAT (3A10,I10)

IDUM=IDUM+1

I=0

1020

I=I+1

READ (5,1030) DEL1(I),LA1(I),STA1(I),AC1(I),HGR1(I),GS1(I),EQ1(I)

HGR1(I)=HGR1(I) + QWSADD

1030 FORMAT (F5.2,I5,5F10.3)

C

C

DEL1(I) - DELIVERY SIZE AT STA1(I)

C

LA1(I) - SIGNAL 1 FOR STATION ON MAIN EXCEPT SUB, THEN 2

C

STA1(I) - ACTUAL STATION ON MAIN

C

AC1(I) - ACRES FOR TURNOUT OFF OF MAIN

C

HGR1(I) - HYDRAULIC GRADE LINE REQUIRED FOR TURNOUT

C

ENTER .09 FOR HGR1(I) TO LOCATE A TANK AT STA1(I)

**** PROGRAM LAKMLP ****

```

C      GS1(I) - NATURAL GROUND SURFACE ON MAIN
C      EQ1(I) - NUMERICAL VALUE OF EQUATION DOWNSTREAM OF STA1(I)
C
      IF (HGR1(I).NE.(DWSADD+.09)) GO TO 1035
      LASAV=I
      STASAV=STA1(I)
      GO TO (1035,1035,1032,1032) ,ITYPE
1032  HGR1(LASAV)=TKWSEL
1035  IF (I.GT.IMAX) GO TO 7100
      IF (LA1(I).EQ.2) GO TO 2000
      IF (LA1(I).EQ.0) GO TO 1040
      GO TO 1020
1040  N1=I-1
      N1L=N1+1
      SAC1(N1+1)=0.0
      DO 1050 I=1,N1
      LI(I)=STA1(I+1)-STA1(I)+EQ1(I)
      N1I=N1+1-I
      SAC1(N1I)=SAC1(N1I+1)+AC1(N1I+1)
1050  CONTINUE
      CALL SACQ (1,SAC1,AC1,Q1,DQ1,N1)
C      IF (ABS (Q1(1)-TQP) .GE. 1.0) GO TO 7800
      IF (ITYPE.NE.1) GO TO 1120
      IF (IG.EQ.1) GO TO 1120
      I=N1
1090  IG=I+1
1100  DO 1110 I=IG,N1
      IF (LA1(I).EQ.2) GO TO 2060
1110  CONTINUE
1120  DO 1190 I=1,N1
      D1=QQ * (Q1(I)**(ZP*2.))
      IF (D1.GT.12.) GO TO 1130
      JX=(D1/2.) +1.
      DIA1(I)=JX*2
      GO TO 1150
1130  IF (D1.GT.54.) GO TO 1140
      JX=(D1/3.) +1.
      DIA1(I)=JX*3
      GO TO 1150
1140  JX=(D1/6.) +1.
      DIA1(I)=JX*6
1150  IF (DIA1(I)-22.) 1160,1160,1170
1160  CS=CSS
      GO TO 1180
1170  CS=CSB
1180  HL1(I)=(((576.*G1(I)) / (PI*CS*DIA1(I)**2.625))**2.) /1000.
      HF1(I)=LI(I)*HL1(I)
1190  CONTINUE

```

**** PROGRAM LAKMLP ****

```

HGL1(N1+1)=HGR1(N1+1)
DO 1200 I=1,N1
N1I=N1+1-I
HGL1(N1I)=HF1(N1I) + HGL1(N1I+1)
IF (HGL1(N1I) .GE. HGR1(N1I)) GO TO 1200
HGL1(N1I)=HGR1(N1I)
IF (ITYPE.NE.4) GO TO 1200
IF (HGR1(N1I).LE.TKWSEL) GO TO 1200
1200  TKWSEL=HGR1(N1I)
CONTINUE
IF (ITYPE.NE.4) GO TO 1205
IF (HGL1(LASAV).GT.TKWSEL) GO TO 1201
IF (TKWSEL.NE.0.0) GO TO 1202
1201  TKWSEL=IFIX(HGL1(LASAV)+1.0)
GO TO 1205
1202  TKWSEL=IFIX(TKWSEL +1.5)
1205  IF (INPUT .NE. 1) GO TO 1240
WRITE (6,1210)
1210  FORMAT (1H1,100H STATION ACRES HGL HGR LENGTH
1 SAC Q DIA HL HF /)
WRITE (6,1010) (LAT1(II),II=1,3)
DO 1230 I=1,N1
WRITE (6,1220) STA1(I),AC1(I),HGL1(I),HGR1(I),L1(I),SAC1(I),Q1(I),
1 DIA1(I),HL1(I),HF1(I)
1220  FORMAT (4F10.2 / 40X,4F10.2,F10.6,F10.2)
1230  CONTINUE
WRITE (6,1220) STA1(N1+1),AC1(N1+1),HGL1(N1+1),HGR1(N1+1)
1240  CONTINUE
N2=0
N3=0
N4=0
N5=0
JY=1
KY=1
LY=1
MY=1
K2=0
K3=0
K4=0
K5=0
PZC=.00007226 / CSB**2.
GO TO (1300,1400,1500,1500) , ITYPE
C
C ITYPE = 1
C
1300  WRITE (JW,1310) CP,HGL1(1),AVH1,ICOUNT,JCOUNT,KCOUNT
1310  FORMAT (4F CP=,F10.4,10X, 10H HGL1(1)=,F10.2,10X, 7H AVH1=,
1 F10.2,3I10)

```

**** PROGRAM LAKMLP ****

```

HVH=HVH1
IF (ABS (HGL1(1)-AVH1) .LE. GDIFF) GO TO 1510
IF (KCOUNT.EQ.2) GO TO 1510
IF (AVH1.LT.HGL1(1)) GO TO 1320
ICOUNT=ICOUNT + 1
IF (ICOUNT.EQ.11) GO TO 7600
CP=CP-.01
IF (JCOUNT.GT.0) GO TO 1340
GO TO 1350
1320 JCOUNT=JCOUNT + 1
IF (JCOUNT.EQ.11) GO TO 7700
CP=CP+.01
IF (ICOUNT.GT.0) GO TO 1330
GO TO 1350
1330 CP=CP-.01
1340 KCOUNT=KCOUNT + 1
CP=CP / (AVH1 / HGL1(1))
1350 QQ=(TQP **ZP) *CP *12.
I=0
JG=1
KG=1
LG=1
MG=1
GO TO 1090

C
C
C      ITYPE = 2
C
1400 AVH1=IFIX(HGL1(1)+1.0)
HVH =AVH1 + 5.0
GO TO 1510

C
C      ITYPE = 3   AND   ITYPE = 4
C
1500 HGL1(LASAV)=TKWSEL
DO 1505 I=2,LASAV
NNI=LASAV + 1 - I
HGL1(NNI)=HFL(NNI) + HGL1(NNI+1)
1505 CONTINUE
AVH1=HGL1(1)
HVH =0.0
1510 WRITE (JW,1520) (LAT1(II),II=1,3),TODAY
1520 FORMAT (1H1,35H      ECONOMICAL PIPE HYDRAULIC STUDY,30X,3A10,30X
1,A10//)
WRITE (7,1521) (LAT1(II),II=1,3),ITYPE,STA1(N1L),TEELDS,AVH1
1521 FORMAT (3A10,I10,3F10.2)
GO TO (1530,1530,1550,1550) ,ITYPE
1530 WRITE (JW,1540) HVH

```

**** PROGRAM LAKMLP ****

```

1540  FORMAT (48X,30H PIPE CLASS DESIGN ELEVATION =,F10.2/)
      WRITE (7,1541) HVH, IDUM
1541  FORMAT (F10.2,I10)
      GO TO 1570
1550  WRITE (JW,1560)
1560  FORMAT(38X,50HPIPE CLASS DESIGN ELEVATION = HYDRAULIC GRADE LINE/
      WRITE (7,1565) IDUM
1565  FORMAT (I10)
1570  GO TO (1660,1640,1580,1600) ,ITYPE
1580  WRITE (JW,1590) TKWSEL,STASAV
1590  FORMAT (28X,39H DOWN TO THE KNOWN TANK WATER SURFACE (,F10.2,
      1 9H ) AT STA,F10.2/)
      WRITE (7,1591) TKWSEL,STASAV
1591  FORMAT (2F10.2)
      GO TO 1620
1600  WRITE (JW,1610) TKWSEL,STASAV
1610  FORMAT (26X,42H DOWN TO THE COMPUTED TANK WATER SURFACE (,F10.2,
      1 9H ) AT STA,F10.2/)
      WRITE (7,1591) TKWSEL,STASAV
1620  IF (STASAV.EQ.STA1(NIL)) GO TO 1650
      WRITE (JW,1630) STASAV,TKWSEL
1630  FORMAT (25X,10H AFTER STA,F10.2,36H ,THE PIPE CLASS DESIGN ELEVATI
      10N = ,F10.2, 10H + 5.0 FT./)
      GO TO 1660
1640  WRITE (JW,1650) AVH1
1650  FORMAT (28X,19H WATER SURFACE IS (,F10.2,37H ) IN THE TANK NEAR TH
      1E PUMPING PLANT/)
1660  WRITE (JW,1670)
1670  FORMAT (* STATION      Q      HGL      DIA      V      HV      SLOPE
      1 LENGTH      LOSS      SUBLATERAL NAME      AC      SAC      DQ      DEL      HGR
      2  NGS          HC*//)
C
      CALL PIPSIZ (LA1,STA1,AC1,L1,SAC1,Q1,HGR1,GS1,AVH1,1,N1,LAT2,IMAX,
      1  IR1,DO1,HGL1,BFL1,EQ1)
      SJEXC=SJEXC + SEXCAV(N1)
      SJBKF=SJBKF + SBKFL(N1)
      I=0
      HVH=HVH1
1680  I=I+1
      IF (I.GT.N1) GO TO 8000
      IF (LA1(I).NE.2) GO TO 1680
C
      SUB
C
      K2=K2+1
      WRITE (JW,1690) (LAT2(I,II),II=1,2),TODAY
1690  FORMAT (I10,35H      ECONOMICAL PIPE HYDRAULIC STUDY,30X,2A10,40X,
      2  A10//)

```

**** PROGRAM LAKMLP ****

```

WRITE (7,1691) (LAT2(I,II),II=1,2),IVALV2(K2)
1591 FORMAT (2A10,I10)
GO TO (1710,1700,1720,1720) ,ITYPE
1700 HVH=AVH1+5.0
1710 AVH2=HGL1(I)-TELOS2(K2)
GO TO 1740
1720 IF (STA1(I).GT.STASAV) GO TO 1730
AVH2=TKWSFL
HVH=HGL1(I)
GO TO 1740
1730 HVH=TKWSEL + 5.0
AVH2=HGL1(I) -TELOS2(K2)
1740 WRITE (JW,1540) HVH
WRITE (7,1541) HVH
WRITE (JW,1670)
JY=N2+1
CALL PTPSIZ (LA2,STA2,AC2,L2,SAC2,Q2,HGR2,GS2,AVH2,JY,N2,LAT3,JMAX
2 ,IR2,OQ2,HGL2,DEL2,EQ2)
SJBKF=SJBKF + SBKFL(N2)
SJEXC=SJEXC + SEXCAV(N2)
N2=N2+1
JB=0
1750 J=JB+JY
JB=JB+1
IF (J.GT.N2) GO TO 1680
IF (LA2(J).NE.3) GO TO 1750
K3=K3+1
WRITE (JW,1690) (LAT3(J,II),II=1,2),TODAY
WRITE (7,1691) (LAT3(J,II),II=1,2),IVALV3(K3)
WRITE (JW,1540) HVH
WRITE (7,1541) HVH
WRITE (JW,1670)
AVH3=HGL2(J)-TELOS3(K3)
KY=N3+1
CALL PTPSIZ (LA3,STA3,AC3,L3,SAC3,Q3,HGR3,GS3,AVH3,KY,N3,LAT4,KMAX
3 ,IR3,OQ3,HGL3,DEL3,EQ3)
SJBKF=SJBKF + SBKFL(N3)
SJEXC=SJEXC + SEXCAV(N3)
N3=N3+1
KB=0
1760 K=KB+KY
KB=KB+1
IF (K.GT.N3) GO TO 1750
IF (LA3(K).NE.4) GO TO 1760
K4=K4+1
WRITE (JW,1690) (LAT4(K,II),II=1,2),TODAY
WRITE (7,1691) (LAT4(K,II),II=1,2),IVALV4(K4)
WRITE (JW,1540) HVH

```

**** PROGRAM LAKMLP ****

```

WRITE (7,1541) HVH
WRITE (JW,1670)
AVH4=HGL3(K)-TELOS4(K4)
LY=N4+1
CALL PIPSIZ (LA4,STA4,AG4,L4,SAG4,Q4,HGR4,GS4,AVH4,LY,N4,LAT5,LMAX
4      ,IR4,DQ4,HGL4,DEL4,EQ4)
SJBKF=SJBKF + SBKFL(N4)
SJEXC=SJEXC + SEXCAV(N4)
N4=N4+1
LB=0
1770  LE=LB+LY
      LB=LB+1
      IF (L.GT.N4) GO TO 1760
      IF (LA4(L).NE.5) GO TO 1770
      K5=K5+1
      WRITE (JW,1690) (LAT5(L,II),II=1,2),TODAY
      WRITE (7,1591) (LAT5(L,II),II=1,2),IVALV5(K5)
      WRITE (JW,1540) HVH
      WRITE (7,1541) HVH
      WRITE (JW,1670)
      AVH5=HGL4(L)-TELOS5(K5)
      MY=N5+1
      CALL PIPSIZ (LA5,STA5,AG5,L5,SAG5,Q5,HGR5,GS5,AVH5,MY,N5,LAT5,MMAX
5      ,IR5,DQ5,HGL5,DEL5,EQ5)
      SJBKF=SJBKF + SBKFL(N5)
      SJEXC=SJEXC + SEXCAV(N5)
      N5=N5+1
      GO TO 1770

C
C      READ IN SUB LATERAL DATA
C      SPACES 2 THROUGH 20
C
2000  READ (5,2010) (LAT2(I,II),II=1,2),IVALVE,TLOSS,TOSS
2010  FORMAT (2A10,I10,2F8.2)
      K2 = K2+1
      IVALV2(K2) = IVALVE
      IF (TLOSS.EQ.0.) GO TO 2015
      TEELOS2(K2) = TLOSS
      TELOS2(K2) = TOSS
      GO TO 2016
2015  TEELOS2(K2) = TEELOS
      TELOS2(K2) = TEELOS
2016  JJ=J+1
2020  J=J+1
      READ (5,1030) DEL2(J),LA2(J),STA2(J),AG2(J),HGR2(J),GS2(J),EQ2(J)
      HGR2(J)=HGR2(J) + DWSADD

C
C      LA2(J) - SIGNAL 2 FOR STATION ON SUB EXCEPT SUB SUB,THEN 3

```

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**** PROGRAM LAKMLP ****

C

```

IF (J.GT.JMAX) GO TO 7200
IF (LA2(J).EQ.3) GO TO 3000
IF (LA2(J).EQ.0) GO TO 2040
GO TO 2020
2040 N2=J-1
SAC2(N2+1)=0.0
GO 2050 J=JJ,N2
L2(J)=STA2(J+1)-STA2(J)+EQ2(J)
N2J=N2+JJ-J
SAC2(N2J)=SAC2(N2J+1)+AC2(N2J+1)
2050 CONTINUE
CALL SACQ (JJ,SAC2,AC2,Q2,DQ2,N2)
IF (ITYPE.NE.1) GO TO 2120
IF (IG.EQ.0) GO TO 2120
2060 K2=K2 +1
GO 2070 J=JG,JMAX
IF (LA2(J).EQ.0) GO TO 2080
2070 CONTINUE
J=JMAX
2080 N2=J-1
JGSAV=JG
GO TO 2100
2090 JG=J+1
2100 GO 2110 J=JG,N2
IF (LA2(J).EQ.3) GO TO 3060
2110 CONTINUE
JJ=JGSAV
2120 GO 2130 J=JJ,N2
D2=Q0 * (Q2(J)**(ZP*2.))
IF (D2.GT.12.) GO TO 2130
JX=(D2/2.) +1.
DIA2(J)=JX*2
GO TO 2150
2130 IF (D2.GT.54.) GO TO 2140
JX=(D2/3.) +1.
DIA2(J)=JX *3
GO TO 2150
2140 JX=(D2/6.) +1.
DIA2(J)=JX * 6
2150 IF (DIA2(J)-22.) 2160,2160,2170
2160 CS=CSS
GO TO 2180
2170 CS=CSR
2180 HL2(J)={((576.*Q2(J)) / (PI*CS*DIA2(J)**2.625))**2.} /1000.
HF2(J)=L2(J)*HL2(J)
2190 CONTINUE
HGL2(N2+1)=HGR2(N2+1)

```

**** PROGRAM LAKMLP ****

```

      DO 2200 J=JJ,N2
      N2J=N2+JJ-J
      HGL2(N2J)=HF2(N2J) + HGL2(N2J+1)
      IF (HGL2(N2J) .GE. HGR2(N2J)) GO TO 2200
      HSL2(N2J)=HGR2(N2J)
2200  CONTINUE
      IF (INPUT .NE. 1) GO TO 2240
      WRITE (5,2210)
2210  FORMAT ( // 100H STATION      ACRES      HGL      HGR      LENGTH
      1  SAC      Q      DIA      HL      HF      /)
      WRITE (5,2010) (LAT2(I,II),II=1,2)
      DO 2230 J=JJ,N2
      WRITE (6,1220) STA2(J),AC2(J),HGL2(J),HGR2(J),L2(J),SAC2(J),Q2(J),
      2  DIA2(J),HL2(J),HF2(J)
2230  CONTINUE
      WRITE (6,1220) STA2(N2+1),AC2(N2+1),HGL2(N2+1),HGR2(N2+1)
2240  CONTINUE
      C
      C      COMPUTE TANK WATER SURFACE ELEVATION
      C
      IF (ITYPE.NE.4) GO TO 2260
      IF (LASAV.EQ.0) GO TO 2250
      IF (I.GE.LASAV) GO TO 2260
2250  IF (HGL2(JJ).LT.TKWSL) GO TO 2260
      TKWSL = HGL2(JJ) + TELOS2(K2)
2260  HGR1(I)=HGL2(JJ) + TELOS2(K2)
      AC1(I)=SAC2(JJ)
      IF (ITYPE.NE.1) GO TO 1020
      IF (IG.EQ. 0) GO TO 1020
      JG=N2+2
      GO TO 1090
      C
      C      READ IN SUB SUB LATERAL DATA
      C      SPACES 2 THROUGH 20
      C
3000  READ (5,2010) (LAT3(J,II),II=1,2),IVALVE,TLOSS,TOSS
      K3 = K3+1
      IVALV3(K3) = IVALVE
      IF (TLOSS.EQ.0.) GO TO 3015
      TELOS3(K3) = TLOSS
      TELOS3(K3) = TOSS
      GO TO 3016
3015  TELOS3(K3) = 2.*TELOS
      TELOS3(K3) = TELOS
3016  KK=K+1
3020  K=K+1
      READ (5,1030) DEL3(K),LA3(K),STA3(K),AC3(K),HGR3(K),GS3(K),FQ3(K)
      HGR3(K)=HGR3(K) + DWSADD

```

**** PROGRAM LAKMLP ****

```

C
C      LA3(K) - SIGNAL 3 FOR STATION ON SUB SUB EXCEPT SSS, THEN 4
C
      IF (K.GT.KMAX) GO TO 7300
      IF (LA3(K).EQ.4) GO TO 4000
      IF (LA3(K).EQ.0) GO TO 3040
      GO TO 3020
3040  N3=K-1
      SAC3(N3+1)=0.0
      DO 3050 K=KK,N3
      L3(K)=STA3(K+1)-STA3(K)+EQ3(K)
      N3K=N3+KK-K
      SAC3(N3K)=SAG3(N3K+1) + AC3(N3K+1)
3050  CONTINUE
      CALL SACQ (KK,SAC3,AC3,Q3,DQ3,N3)
      IF (ITYPE.NE.1) GO TO 3120
      IF (IG.EQ.0) GO TO 3120
3060  K3=K3+1
      DO 3070 K=KG,KMAX
      IF (LA3(K).EQ.1) GO TO 3080
3070  CONTINUE
      K=KMAX
3080  N3=K-1
      KGSAV=KG
      GO TO 3100
3090  KG=K+1
3100  DO 3110 K=KG,N3
      IF (LA3(K).EQ.4) GO TO 4060
3110  CONTINUE
      KK=KGSAV
3120  DO 3190 K=KK,N3
      D3=D3 * (Q3(K)**(ZP*2.))
      IF (D3.GT.12.) GO TO 3130
      JX=(D3/2.) +1.
      DIA3(K)=JX*2
      GO TO 3150
3130  IF (D3.GT.54.) GO TO 3140
      JX=(D3/3.) +1.
      DIA3(K)=JX*3
      GO TO 3150
3140  JX=(D3/6.) +1.
      DIA3(K)=JX*6
3150  IF (DIA3(K)-22.) 3160,3160,3170
3160  CS=CSS
      GO TO 3180
3170  CS=CSB
3180  HL3(K)=(((575.*Q3(K)) / (PI*CS*DIA3(K)**2.625))**2.) /1000.
      HF3(K)=L3(K)*HL3(K)

```

**** PROGRAM LAKMLP ****

```

3190  CONTINUE
      HGL3(N3+1)=HGR3(N3+1)
      DO 3200 K=KK,N3
      N3K=N3+KK-K
      HGL3(N3K)=HF3(N3K) + HGL3(N3K+1)
      IF (HGL3(N3K).GE. HGR3(N3K)) GO TO 3200
      HGL3(N3K)=HGR3(N3K)
3200  CONTINUE
      IF (INPUT .NE. 1) GO TO 3240
      WRITE (6,2210)
      WRITE (6,2010) (LAT3(J,II),II=1,2)
      DO 3230 K=KK,N3
      WRITE (6,1220) STA3(K),AC3(K),HGL3(K),HGR3(K),L3(K),SAC3(K),Q3(K),
3    DIA3(K),HL3(K),HF3(K)
3230  CONTINUE
      WRITE (6,1220) STA3(N3+1),AC3(N3+1),HGL3(N3+1),HGR3(N3+1)
3240  CONTINUE
      HGR2(J)=HGL3(KK) +TELOS3(K3)
      AC2(J)=SAC3(KK)
      IF (ITYPE.NE.1) GO TO 2020
      IF (IG.EQ. 0) GO TO 2020
      K3=N3+2
      GO TO 2090

C
C      READ IN SUB SUB SUB LATERAL DATA
C      SPACES 2 THROUGH 20
C
4000  READ (5,2010) (LAT4(K,II),II=1,2),IVALVE,TLOSS,TOSS
      K4 = K4+1
      IVALV4(K4) = TVALVE
      IF (TLOSS.EQ.0.) GO TO 4015
      TEELOS4(K4) = TLOSS
      TELOS4(K4) = TOSS
      GO TO 4016
4015  TEELOS4(K4) = 3.*TEELOS
      TELOS4(K4) = TEELOS
4016  LL=L+1
4020  L=L+1
      READ (5,1030) DEL4(L),LA4(L),STA4(L),AC4(L),HGR4(L),GS4(L),EQ4(L)
      HGR4(L)=HGR4(L) + QWSADD

C
C      LA4(L) - SIGNAL 4 FOR STATION ON SUBSUBSUB EXCEPT SSSS, THEN 5
C
      IF (L.GT.LMAX) GO TO 7400
      IF (LA4(L).EQ.5) GO TO 5000
      IF (LA4(L).EQ.0) GO TO 4040
      GO TO 4020
4040  N4=L-1

```

**** PROGRAM LAKMLP ****

```

SAC4(N4+1)=0.0
DO 4050 L=LL,N4
L4(L)=STA4(L+1)-STA4(L)+EQ4(L)
N4L=N4+LL-L
SAC4(N4L)=SAC4(N4L+1) + AC4(N4L+1)
4050 CONTINUE
CALL SACQ (LL,SAC4,AC4,Q4,QQ4,N4)
IF (ITYPE.NE.1) GO TO 4120
IF (IG.EQ.0) GO TO 4120
4060 K4=K4+1
DO 4070 L=LG,LMAX
IF (L44(L).EQ.0) GO TO 4080
4070 CONTINUE
L=LMAX
4080 N4=L-1
LGSAV=LG
GO TO 4100
4090 LG=L+1
4100 DO 4110 L=LG,N4
IF (L44(L).EQ.5) GO TO 5060
4110 CONTINUE
LL=LGSAV
4120 DO 4130 L=LL,N4
D4=DQ * (Q4(L)**(ZP*2.))
IF (D4.GT.12.) GO TO 4130
JX=(D4/2.) +1.
DIA4(L)=JX*2
GO TO 4150
4130 IF (D4.GT.34.) GO TO 4140
JX=(D4/3.) +1.
DIA4(L)=JX*3
GO TO 4150
4140 JX=(D4/6.) +1.
DIA4(L)=JX*6
4150 IF (DIA4(L)-22.) 4160,4160,4170
4160 CS=CSS
GO TO 4180
4170 CS=CS3
4180 HL4(L)=(((576.*Q4(L)) / (PI*CS*DIA4(L)**2.625))**2.) /1000.
HF4(L)=L4(L)*HL4(L)
4190 CONTINUE
HGL4(N4+1)=HGR4(N4+1)
DO 4200 L=LL,N4
N4L=N4+LL-L
HGL4(N4L)=HF4(N4L) + HGL4(N4L+1)
IF (HGL4(N4L).GE. HGR4(N4L)) GO TO 4200
HGL4(N4L)=HGR4(N4L)
4200 CONTINUE

```

**** PROGRAM LAKMLP ****

```

      IF (INPUT .NE. 1) GO TO 4240
      WRITE (6,2210)
      WRITE (6,2310) (LAT4(K,II),II=1,2)
      DO 4230 L=LL,N4
      WRITE (6,1220) STA4(L),AC4(L),HGL4(L),HGR4(L),L4(L),SAC4(L),Q4(L),
4     DIA4(L),HL4(L),HF4(L)
4230  CONTINUE
      WRITE (6,1220) STA4(N4+1),AC4(N4+1),HGL4(N4+1),HGR4(N4+1)
4240  CONTINUE
      HGR3(K)=HGL4(LL) +TELOS4(K4)
      AC3(K)=SAC4(LL)
      IF (ITYPE.NE.1) GO TO 3020
      IF (IG.EQ. 0) GO TO 3020
      LG=N4+2
      GO TO 3090

C
C     READ IN SUB SUB SUB SUB LATERAL DATA
C     SPACES 2 THROUGH 20
C
5000  READ (5,2010) (LAT5(L,II),II=1,2),IVALVE,TLOSS,TOSS
      K5 = K5+1
      IVALV5(K5) = IVALVE
      IF (TLOSS.EQ.0.) GO TO 5015
      TEELOS5(K5) = TLOSS
      TELOS5(K5) = TOSS
      GO TO 5016
5015  TEELOS5(K5) = 4.*TEELOS
      TELOS5(K5) = TEELOS
5016  M=M+1
5020  M=M+1
      READ (5,1030) DEL5(M),LA5(M),STA5(M),AC5(M),HGR5(M),GS5(M),EQ5(M)
      HGR5(M)=HGR5(M) + DWSADD

C
C     LA5(M) - SIGNAL 5 FOR STATION ON SUB SUR SUR SUR
C
      IF (M.GT.MMAX) GO TO 7500
      IF (LA5(M).EQ.0) GO TO 5040
      GO TO 5020
5040  N5=M-1
      SAC5(N5+1)=0.0
      DO 5050 M=M,N5
      L5(M)=STA5(M+1)-STA5(M)+EQ5(M)
      N5M=N5+M+M-M
      SAC5(N5M)=SAC5(N5M+1) + AC5(N5M+1)
5050  CONTINUE
      CALL SACQ (MM,SAC5,AC5,Q5,DQ5,N5)
      IF (ITYPE.NE.1) GO TO 5120
      IF (IG.EQ.0) GO TO 5120

```

**** PROGRAM LAKMLP ****

```

5060  K5=K5+1
      DO 5070 M=MG,MMAX
      IF (LA5(M).EQ.0) GO TO 5080
5070  CONTINUE
      M=MMAX
5080  N5=M-1
      MGSAY=MG
      MM=MGSAY
5120  DO 5190 M=MM,N5
      D5=Q0 * (Q5(M)**(ZP*2.))
      IF (D5.GT.12.) GO TO 5130
      JX=(D5/2.) +1.
      DIA5(M)=JX*2
      GO TO 5150
5130  IF (D5.GT.54.) GO TO 5140
      JX=(D5/3.) +1.
      DIA5(M)=JX*3
      GO TO 5150
5140  JX=(D5/6.) +1.
      DIA5(M)=JX*6
5150  IF (DIA5(M)-22.) 5160,5160,5170
5160  CS=CSS
      GO TO 5180
5170  CS=CSB
5180  HL5(M)=(((576.*Q5(M)) / (PI*CS*DIA5(M)**2.625))**2.) /1000.
      HF5(M)=L5(M)*HL5(M)
5190  CONTINUE
      HGL5(N5+1)=HGR5(N5+1)
      DO 5220 M=MM,N5
      N5M=N5+MM-M
      HGL5(N5M)=HF5(N5M) + HGL5(N5M+1)
      IF (HGL5(N5M).GE. HGR5(N5M)) GO TO 5200
      HGL5(N5M)=HGR5(N5M)
5200  CONTINUE
      IF (INPUT.NE.1) GO TO 5240
      WRITE (6,2210)
      WRITE (6,2310) (LAT5(L,IT),II=1,2)
      DO 5230 M=MM,N5
      WRITE (6,1220) STA5(M),AC5(M),HGL5(M),HGR5(M),L5(M),SAC5(M),Q5(M),
5      DIA5(M),HL5(M),HF5(M)
5230  CONTINUE
      WRITE (6,1220) STA5(N5+1),AC5(N5+1),HGL5(N5+1),HGR5(N5+1)
5240  CONTINUE
      HGR4(L)=HGL5(MM) #TELOS5(K5)
      AC4(L)=SAC5(MM)
      IF (ITYPE.NE.1) GO TO 4020
      IF (IG.EQ.0) GO TO 4020
      MG=N5+2

```

**** PROGRAM LAKMLP ****

GO TO 4000

C
C
C

WRITE INPUT ERROR MESSAGES

7100 IJ=I-1

WRITE (6,7110) (LAT1(IJ),IJ=1,3),IO,STA1(IJ),I

7110 FORMAT (1H1,48X,3A10/// 6H STA1(,I3, 3H) =,F10.3/// 10X, 4H I =,I3/
177 85H DIMENSION AND IMAX MUST BE INCREASED TO THE NUMBER OF STATIONS ON THE MAIN (1) LINE.)

GO TO 30

7200 JJ=J-1

WRITE (6,7210) (LAT2(I,IJ),IJ=1,2),JO,STA2(JJ),J

7210 FORMAT (1H1,48X,2A10/// 6H STA2(,I3, 3H) =,F10.3/// 10X, 4H J =,I3/
277 88H DIMENSION AND JMAX MUST BE INCREASED TO THE NUMBER OF STATIONS ON THE SUB (2) LATERALS.)

GO TO 30

7300 KJ=K-1

WRITE (6,7310) (LAT3(J,IJ),IJ=1,2),KO,STA3(KJ),K

7310 FORMAT (1H1,48X,2A10/// 6H STA3(,I3, 3H) =,F10.3/// 10X, 4H K =,I3/
377 92H DIMENSION AND KMAX MUST BE INCREASED TO THE NUMBER OF STATIONS ON THE SUB SUB (3) LATERALS.)

GO TO 30

7400 LJ=L-1

WRITE (6,7410) (LAT4(K,IJ),IJ=1,2),LO,STA4(LJ),L

7410 FORMAT (1H1,48X,2A10/// 6H STA4(,I3, 3H) =,F10.3/// 10X, 4H L =,I3/
477 95H DIMENSION AND LMAX MUST BE INCREASED TO THE NUMBER OF STATIONS ON THE SUB SUB SUB (4) LATERALS.)

GO TO 30

7500 MJ=M-1

WRITE (6,7510) (LAT5(L,IJ),IJ=1,2),MO,STA5(MJ),M

7510 FORMAT (1H1,48X,2A10/// 6H STA5(,I3, 3H) =,F10.3/// 10X, 4H M =,I3/
577 100H DIMENSION AND MMAX MUST BE INCREASED TO THE NUMBER OF STATIONS ON THE SUB SUB SUB SUB (5) LATERALS.)

GO TO 30

7600 WRITE (6,7610) CP

7610 FORMAT (1H1/////10X, 25H CP MUST BE DECREASED TO ,F10.3)
GO TO 30

7700 WRITE (6,7710) CP

7710 FORMAT (1H1/////10X, 25H CP MUST BE INCREASED TO ,F10.3)
GO TO 30

8000 I=0

IF (ITYPE.GT.2) GO TO 8005

TKWSEL=AVH1

8005 J=0

II=0

IF (L1(1).EQ.0) GO TO 9000

8010 I=I+1

IP=IR1(I)

**** PROGRAM LAKMLP ****

```

IF(LA1(I).EQ.0) GO TO 8200
IF(IP.EQ.0) GO TO 8010
RL(IP)=L1(I)
II=1
GZ(IP,1)=IP+1
IF(L1(I+1).EQ.0.0) GO TO 8025
IF(LA1(I+1).EQ.2) GO TO 8100
8020 RHS(IP)=TKWSEL-HGR1(I+1)
GO TO 8010
8025 IF(LA1(I+1).EQ.0) GO TO 8075
IF(LA1(I+1).EQ.2) GO TO 8040
IF(LA1(I+1).NE.LA1(I+2)) GO TO 8030
IF(HGR1(I+1).GT.HGR1(I+2)) GO TO 8020
RHS(IP)=TKWSEL-HGR1(I+2)
GO TO 8010
8030 IF(LA1(I+2).EQ.0) GO TO 8035
RHS(IP)=TKWSEL-HGR1(I+1)
GO TO 8105
8035 IF(HGR1(I+1).GT.HGR1(I+2)) GO TO 8080
RHS(IP)=TKWSEL-HGR1(I+2)
GO TO 8085
8040 IF(LA1(I+1).NE.LA1(I+2)) GO TO 8070
RHS(IP)=TKWSEL-GS1(I+1)
8045 J=J+1
II=II+1
GZ(IP,II)=IR2(J)
8050 J=J+1
IF(LA2(J).EQ.0) GO TO 8060
GO TO 8050
8060 IF(II.EQ.3) GO TO 8010
GO TO 8045
8070 RHS(IP)=TKWSEL-HGR1(I+2)
GO TO 8105
8075 IF(L1(I).EQ.0.0) GO TO 8090
8080 RHS(IP)=TKWSEL-HGR1(I+1)
8085 GZ(IP,1)=0
GO TO 8010
8090 IP=IR1(I-1)
GO TO 8085
8100 RHS(IP)=TKWSEL-GS1(I+1)
8105 J=J+1
II=II+1
GZ(IP,II)=IR2(J)
8120 J=J+1
IF(LA2(J).EQ.0) GO TO 8010
GO TO 8120
8200 JA=0
K2=1

```

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**** PROGRAM LAKMLP ****

```

      K=0
      II=0
      JY=1
      IF (L2(1).EQ.0) GO TO 9000
8210  J=JA+JY
      JA=JA+1
      IP=IR2(J)
      IF(LA2(J).EQ.0) GO TO 8295
      IF(IP.EQ.0) GO TO 8210
      RL(IP)=L2(J)
      II=1
      GZ(IP,1)=IP+1
      IF(L2(J+1).EQ.0.0) GO TO 8225
      IF(LA2(J+1).EQ.3) GO TO 8300
8220  RHS(IP)=TKWSEL-HGR2(J+1)-TEELOS2(K2)
      GO TO 8210
8225  IF(LA2(J+1).EQ.0) GO TO 8275
      IF(LA2(J+1).EQ.3) GO TO 8240
      IF(LA2(J+1).NE.LA2(J+2)) GO TO 8230
      IF(HGR2(J+1).GT.HGR2(J+2)) GO TO 8220
      RHS(IP)=TKWSEL-HGR2(J+2)-TEELOS2(K2)
      GO TO 8210
8230  IF(LA2(J+2).EQ.1) GO TO 8235
      RHS(IP)=TKWSEL-HGR2(J+1)-TEELOS2(K2)
      GO TO 8305
8235  IF(HGR2(J+1).GT.HGR2(J+2)) GO TO 8280
      RHS(IP)=TKWSEL-HGR2(J+2)-TEELOS2(K2)
      GO TO 8285
8240  IF(LA2(J+1).NE.LA2(J+2)) GO TO 8270
      RHS(IP)=TKWSEL-GS2(J+1)
8245  K=K+1
      II=II+1
      GZ(IP,II)=IR3(K)
8250  K=K+1
      IF(LA3(K).EQ.1) GO TO 8255
      GO TO 8250
8260  IF(II.FO.3) GO TO 8210
      GO TO 8245
8270  RHS(IP)=TKWSEL-HGR2(J+2)-TEELOS2(K2)
      GO TO 8305
8275  IF(L2(J).EQ.0.0) GO TO 8290
8280  RHS(IP)=TKWSEL-HGR2(J+1)-TEELOS2(K2)
8285  GZ(IP,1)=0
      GO TO 8210
8290  IP=IR2(J-1)
      GO TO 8285
8295  JY=J+1
      JA=0

```

**** PROGRAM LAKMLP ****

```
K2=K2+1
IF (LA2(J+1).EQ.0) GO TO 8400
GO TO 8210
8300 RHS(IP)=TKWSEL-GS2(J+1)
8305 K=K+1
      II=II+1
      GZ(IP,II)=IR3(K)
8320 K=K+1
      IF(LA3(K).EQ.0) GO TO 8210
      GO TO 8320
8400 KA=0
      K3=1
      L=0
      II=0
      KY=1
      IF(L3(1).EQ.0) GO TO 9000
8410 K=KA+KY
      KA=KA+1
      IP=IR3(K)
      IF(LA3(K).EQ.0) GO TO 8495
      IF(IP.EQ.0) GO TO 8410
      RL(IP)=L3(K)
      II=1
      GZ(IP,1)=IP+1
      IF(L3(K+1).EQ.0.0) GO TO 8425
      IF(LA3(K+1).EQ.4) GO TO 8500
8420 RHS(IP)=TKWSEL-HGR3(K+1)-TEELOS3(K3)
      GO TO 8410
8425 IF(LA3(K+1).EQ.0) GO TO 8475
      IF(LA3(K+1).EQ.4) GO TO 8440
      IF(LA3(K+1).NE.LA3(K+2)) GO TO 8430
      IF(HGR3(K+1).GT.HGR3(K+2)) GO TO 8420
      RHS(IP)=TKWSEL-HGR3(K+2)-TEELOS3(K3)
      GO TO 8410
8430 IF(LA3(K+2).EQ.0) GO TO 8435
      RHS(IP)=TKWSEL-HGR3(K+1)-TEELOS3(K3)
      GO TO 8505
8435 IF(HGR3(K+1).GT.HGR3(K+2)) GO TO 8480
      RHS(IP)=TKWSEL-HGR3(K+2)-TEELOS3(K3)
      GO TO 8485
8440 IF(LA3(K+1).NE.LA3(K+2)) GO TO 8470
      RHS(IP)=TKWSEL-GS3(K+1)
8445 L=L+1
      II=II+1
      GZ(IP,II)=IR4(L)
8450 L=L+1
      IF(LA4(L).EQ.0) GO TO 8460
      GO TO 8450
```

**** PROGRAM LAKMLP ****

```

8460 IF(II.EQ.3) GO TO 8410
      GO TO 8445
8470 RHS(IP)=TKWSEL-HGR3(K+2)-TEELOS3(K3)
      GO TO 8505
8475 IF(L3(K).EQ.0.0) GO TO 8490
8480 RHS(IP)=TKWSEL-HGR3(K+1)-TEELOS3(K3)
8485 GZ(IP,1)=0
      GO TO 8410
8490 IP=IR3(K-1)
      GO TO 8485
8495 KY=K+1
      KA=0
      K3=K3+1
      IF (LA3(K+1).EQ.0) GO TO 8500
      GO TO 8410
8500 RHS(IP)=TKWSEL-GS3(K+1)
8505 L=L+1
      II=II+1
      GZ(IP,II)=IR4(L)
8520 L=L+1
      IF(LA4(L).EQ.0) GO TO 8410
      GO TO 8520
8500 LA=0
      K4=1
      M=0
      II=0
      LY=1
      IF (L4(1).EQ.0) GO TO 9000
8510 L=LA+LY
      LA=LA+1
      IP=IR4(L)
      IF(LA4(L).EQ.0) GO TO 8595
      IF(IP.EQ.0) GO TO 8510
      RL(IP)=L4(L)
      IT=1
      GZ(IP,1)=IP+1
      IF(L4(L+1).EQ.0.0) GO TO 8625
      IF(LA4(L+1).EQ.5) GO TO 8700
8620 RHS(IP)=TKWSEL-HGR4(L+1)-TEELOS4(K4)
      GO TO 8510
8625 IF(LA4(L+1).EQ.0) GO TO 8675
      IF(LA4(L+1).EQ.5) GO TO 8640
      IF(LA4(L+1).NE.LA4(L+2)) GO TO 8630
      IF(HGR4(L+1).GT.HGR4(L+2)) GO TO 8620
      RHS(IP)=TKWSEL-HGR4(L+2)-TEELOS4(K4)
      GO TO 8510
8630 IF(LA4(L+2).EQ.0) GO TO 8635
      RHS(IP)=TKWSEL-HGR4(L+1)-TEELOS4(K4)

```

**** PROGRAM LAKMLP ****

```

      GO TO 8705
8635  IF(HGR4(L+1).GT.HGR4(L+2)) GO TO 8680
      RHS(IP)=TKWSEL-HGR4(L+2)-TEELOS4(K4)
      GO TO 8685
8640  IF(LA4(L+1).NE.LA4(L+2)) GO TO 8670
      RHS(IP)=TKWSEL-GS4(L+1)
8645  M=M+1
      II=II+1
      GZ(IP,II)=IR5(M)
8650  M=M+1
      IF(LA5(M).EQ.0) GO TO 8660
      GO TO 8650
8660  IF(II.EQ.3) GO TO 8610
      GO TO 8645
8670  RHS(IP)=TKWSEL-HGR4(L+2)-TEELOS4(K4)
      GO TO 8705
8675  IF(L4(L).EQ.0.0) GO TO 8690
8680  RHS(IP)=TKWSEL-HGR4(L+1)-TEELOS4(K4)
8685  GZ(IP,1)=0
      GO TO 8610
8690  IP=IR4(L-1)
      GO TO 8685
8695  LY=L+1
      LA=0
      K4=K4+1
      IF (LA4(L+1).EQ.0) GO TO 8800
      GO TO 8610
8700  RHS(IP)=TKWSEL-GS4(L+1)
8705  M=M+1
      II=II+1
      GZ(IP,II)=IR5(M)
8720  M=M+1
      IF(LA5(M).EQ.0) GO TO 8610
      GO TO 8720
8800  MA=1
      LS=1
      II=0
      MY=1
      IF (L5(1).EQ.0) GO TO 9000
8810  M=MA+MY
      MA=MA+1
      IP=IP5(M)
      IF(LA5(M).EQ.0) GO TO 8895
      IF(IP.EQ.0) GO TO 8810
      RL(IP)=L5(M)
      II=1
      GZ(IP,1)=IP+1
      IF(L5(M+1).EQ.0.0) GO TO 8825

```


**** PROGRAM LAKMLP ****

```

9050 CONTINUE
      WRITE (JW,9055) (I,I=1,IC)
9055 FORMAT (10(1X,5H E H,I4))
      DO 9060 I=1,IC
      WRITE (1,9056) I
9056 FORMAT (5H E H,I4)
9060 CONTINUE
      WRITE (JW,9065) (I,I=1,IC)
9065 FORMAT (10(1X,5H L S,I4))
      DO 9070 I=1,IC
      WRITE (1,9066) I
9066 FORMAT (5H L S,I4)
9070 CONTINUE
      WRITE (JW,9080)
9080 FORMAT (1X,7HCOLUMNS)
      WRITE (1,9081)
9081 FORMAT (7HCOLUMNS)
      DO 9090 J=1,IC
      I1=5*J-4
      I2=I1+4
      K1=0
      ICOST=0
      DO 9095 I=I1,I2
      K1=K1+1
      K=J*10 + K1
      IDP=DP(I)
      IHC=HCC(I)
      IF (COSTPI(I).NE.0.0) GO TO 9084
      WRITE (JW,9083) K
9083 FORMAT (1X,*COST OF PIPE *,I10,* = 0.0*)
      ICOST=ICOST+1
9084 WRITE (JW,9085) K,COSTPI(I),IDP,VP(I),IHC,J,J,HP(I)
9085 FORMAT (1X,5H X,I4,6H C,3X,F10.2,3X,I4,*-INCH VEL=*,
1 F5.1,* H*,I5,
2 5H L,I3,6X,3H 1.,
3 6H H,I3,6X,F10.6)
      WRITE (1,9086) K,COSTPI(I),K,J,K,J,HP(I)
9086 FORMAT ( 5H X,I4,6H C,9X,F10.2/
1 5H X,I4,6H L,I3,6X,3H 1./
2 5H X,I4,6H H,I3,6X,F10.6)
9090 CONTINUE
      IF (ICOST.GE.1) CALL EXIT
      DO 9100 I=1,IC
      WRITE (JW,9093) I,I,I,I
9093 FORMAT (1X,5H F,I3,7H S,I3,6X,3H 1.,
1 1X,5H F,I3,7H H,I3,6X,3H-1.)
      WRITE (1,9094) I,I,I,I
9094 FORMAT (5H F,I3,7H S,I3,6X,3H 1./

```

**** PROGRAM LAKMLP ****

```

1          5H      F,I3,7H      H,I3,6X,3H-1.)
DO 9100 J=1,16
  IGZ=GZ(I,J)
  IF (GZ(I,J).EQ.0) GO TO 9100
  WRITE (JW,9097) I,IGZ
9097      FORMAT (1X,5H      F,I3,7H      H,I3,6X,3H 1.)
  WRITE (1,9098) I,IGZ
9098      FORMAT ( 5H      F,I3,7H      H,I3,6X,3H 1.)
9100      CONTINUE
C
C          WRITE RIGHT HAND SIDE
C
  WRITE (JW,9110)
9110      FORMAT (1X,3HRHS)
  WRITE (1,9111)
9111      FORMAT ( 3HRHS)
  DO 9120 I=1,IC
  WRITE (JW,9115) I,RL(I)
9115      FORMAT (1X,15H      RHS      L,I3,6X,F10.2)
  WRITE (1,9115) I,RL(I)
9116      FORMAT (15H      RHS      L,I3,6X,F10.2)
9120      CONTINUE
  DO 9130 I=1,IC
  WRITE (JW,9125) I,RHS(I)
9125      FORMAT (1X,15H      RHS      S,I3,6X,F10.4)
  WRITE (1,9125) I,RHS(I)
9126      FORMAT ( 15H      RHS      S,I3,6X,F10.4)
9130      CONTINUE
  WRITE (JW,9140)
9140      FORMAT (1X,6HENDATA)
  WRITE (1,9141)
9141      FORMAT (6HENDATA)
9999      CALL EXIT
  END

SUBROUTINE FIPSIZ (LA,STA,AC,L,SAC,Q,HGR,GS,AVH,IS,N,LAT,LATDIM ,
1 IR,DQ,HGL,DEL,E)
  COMMON NN,MDIA( 650),GL( 650),MHC( 650),SEXCAV(300),SRKFL(300),
1 ZG,PIPCOV,HVH,PIPMIN,NO,GOEL( 600),JHC( 600),LASAV,TKWSEL,
2 GSS,CSR,SJEXC,SJBKF,MDEL,JW
  COMMON /LPPACK/ DP(2000),VP(2000),HP(2000),HVP(2000),
1 COSTPI(2000),C(30,40),RL(400),GZ(400,16),RHS(400),
2 HCC(2000),IC
  DIMENSION PIPARR(30),IR( 1 )
  DIMENSION LAT( 1 ),STA( 1 ),AC( 1 ),L( 1 ),SAC( 1 ),DQ( 1 ),
1 HGR( 1 ),GS( 1 ),LAT(LATDIM,1),DQ( 1 ),HGL( 1 ),DEL( 1 ),
2 EQ( 1 ),
2 H(300),DIA(300),HF(300),OZG(300),R(300),V(300),HV(300),
3 SL(300),HC(300),DIAOD(300),TWIDTH(300),SP(300)

```

**** PROGRAM LAKMLP ****

REAL L

3
C
3

DATA ARRAY IS FOR PIPE 4" TO 120"

DATA (PIPARR(I),I=1,30) /4.,6.,8.,10.,12.,15.,18.,21.,24.,27.,30.,
1 33.,36.,39.,42.,45.,48.,51.,54.,57.,60.,66.,72.,78.,84.,90.,96.,102.,
2 108.,114.,120./

IF (LA(IS).NE.1) GO TO 5

IP =PIPMIN/2.-1.

IRC=0

IC=0

IL=0

5 IPEMAX=650

NDEMAX=500

JCOUNT=0

HVHCK=0.0

JA=0

NNI=0

10 I=JA+IS

JA=JA+1

IF (LA(I).NE.0) GO TO 10

N=I-1

NL=N+1

SC=10.

IY=IS

20 DO 30 I=IY,N

IF (HGR(I).GE.AVH) GO TO 2000

C IF (STA(I+1).LE.STA(I)) GO TO 2100

30 CONTINUE

IF (JCOUNT.GT.0) GO TO 9999

DO 50 I=IS,N

QZG(I)=Q(I)**ZG

R(I)=QZG(I) / QZG(IS)

IF (I.EQ.IS) GO TO 40

SL(I)=SL(I-1) + R(I) * L(I)

IF (SL(I).EQ.0.0) GO TO 60

GO TO 50

40 SL(I)=R(I) * L(I)

IF (SL(I).EQ.0.0) GO TO 60

50 S=(AVH-HGR(I+1)) / SL(I)

IF (S.GE.SC) GO TO 60

SC=S

ISAV=I

60 CONTINUE

HGL(IS)=AVH

XP=1. /2.625

CA=3.14159 * CSS

CB=3.14159 * CSB

**** PROGRAM LAKMLP ****

```

DO 100 J=IS,ISAV
SP(J)=SC * R(J)
J=((576.*C(J)) / (CB * SQRT(1000.*SP(J)))) ** XP
IF (D.GE.24.0) GO TO 80
J=((576.*C(J)) / (CA * SQRT(1000.*SP(J)))) ** XP
IF (D.GT.PIPMIN) GO TO 70
DIA(J)=PIPMIN
GO TO 100
70 IF (D.GE.12.0) GO TO 80
JX=D/2.0
DIA(J)=JX*2
GO TO 100
80 IF (D.GE.54.0) GO TO 90
JX=D/3.0
DIA(J)=JX*3
GO TO 100
90 JX=D/5.0
DIA(J)=JX*5
100 CONTINUE
II=IS
110 DO 150 I=II,ISAV
IF (DIA(I)-22.0) 120,120,130
120 CX=CA
GO TO 140
130 CX=CB
140 H(I)=(331.776 * J(I)*Q(I)) / (CX * CX * DIA(I)**5.25)
HF(I)=L(I)*H(I)
HGL(I+1)=HGL(I)-HF(I)
IF (HGL(I+1).GE.HGR(I+1)) GO TO 150
GO TO 160
150 CONTINUE
GO TO 210
160 SH=H(IS)-SP(IS)
DO 170 J=IS,I
IF ((H(J)-SP(J)).LT.SH) GO TO 170
SH=H(J)-SP(J)
JKEEP=J
170 CONTINUE
J=JKEEP
IF (DIA(J).GE.12.0) GO TO 180
DIA(J)=DIA(J)+ 2.0
IF (J.EQ.IS) GO TO 200
II=J-1
GO TO 110
180 IF (DIA(J).GE.54.0) GO TO 190
DIA(J)=DIA(J)+ 3.0
IF (J.EQ.IS) GO TO 200
II=J-1

```

**** PROGRAM LAKMLP ****

```

      GO TO 110
190   DIA(J)=DIA(J)+ 5.0
      IF (J.EQ.IS) GO TO 200
      II=J-1
      GO TO 110
200   II=J
      GO TO 110
215   IF (ISAV.EQ.N) GO TO 290
1000  ISAV=ISAV + 1
      SC=10.
      SL(ISAV-1)=0.0
      DO 1060 K=ISAV,N
      IF(QZG(K).EQ.0.0) GO TO 1060
      R(K)=QZG(K) / QZG(ISAV)
      SL(K)=SL(K-1) + R(K) * L(K)
      IF(SL(K).EQ.0.0) GO TO 1060
      S=(HGL(ISAV)-HGR(K+1)) / SL(K)
      IF (S.GE.SC) GO TO 1060
      SC=S
      KSAV=K
1060  CONTINUE
      <=N
      IF (SC.LT. 10.) GO TO 1065
      DO 1063 J=ISAV,N
      IF (DIA(J-1).EQ.0.0) GO TO 1063
      DIA(J)=DIA(J-1)
      SP(J)=S*R(J)
1063  CONTINUE
      <SAV=K
      GO TO 1105
1065  DO 1100 K=ISAV,KSAV
      SP(K)=SC * R(K)
      D=((576.*Q(K)) / (CB * SQRT(1000.*SP(K)))) ** XP
      IF (D.GE.24.0) GO TO 1070
      D=((576.*Q(K)) / (CA * SQRT(1000.*SP(K)))) ** XP
      IF (D.GT.PIPMIN) GO TO 1070
      DIA(K)=PIPMIN
      GO TO 1100
1070  IF (D.GE.12.0) GO TO 1080
      JX=D/2.0
      DIA(K)=JX*2
      GO TO 1100
1080  IF (D.GE.54.0) GO TO 1090
      JX=D/3.0
      DIA(K)=JX*3
      GO TO 1100
1090  JX=D/5.0
      DIA(K)=JX*5

```

**** PROGRAM LAKMLP ****

```

1100 CONTINUE
1105 II=ISAV
1110 DO 1150 I=II,KSAV
      IF (DIA(I)-22.0) 1120,1120,1130
1120 CX=CA
      GO TO 1140
1130 CX=CB
1140 H(I)=(381.776 * Q(I)*Q(I)) / (CX * CX * DIA(I)**5.25)
      HF(I)=L(I)*H(I)
      HGL(I+1)=HGL(I)-HF(I)
      IF (HGL(I+1).GE.HGR(I+1)) GO TO 1150
      GO TO 1150
1150 CONTINUE
      I=KSAV
      GO TO 1210
1160 SH=H(ISAV)-SP(ISAV)
      DO 1170 J=ISAV,I
      IF ((H(J)-SP(J)).LT.SH) GO TO 1170
      SH=H(J)-SP(J)
      JKEEP=J
1170 CONTINUE
      J=JKEEP
      IF (DIA(J).GE.12.0) GO TO 1180
      DIA(J)=DIA(J)+ 2.0
      IF (J.EQ.ISAV) GO TO 1200
      II=J-1
      GO TO 1110
1180 IF (DIA(J).GE.54.0) GO TO 1190
      DIA(J)=DIA(J)+ 3.0
      IF (J.EQ.ISAV) GO TO 1200
      II=J-1
      GO TO 1110
1190 DIA(J)=DIA(J)+ 6.0
      IF (J.EQ.ISAV) GO TO 1200
      II=J-1
      GO TO 1110
1200 II=J
      GO TO 1110
1210 IF (KSAV.EQ.N) GO TO 2900
      ISAV=KSAV
      GO TO 1000

C
C      WRITE INPUT ERROR MESSAGES
C
2000 WRITE (6,2010) HGR(I),STA(I),AVH
2010 FORMAT (//10X, 4H HGR,F10.2, 7H AT STA,F10.2, 32H TS GREATER THAN
FOR EQUAL TO AVH,F10.2)
      JCOUNT=1

```

**** PROGRAM LAKMLP ****

```

      IY=I+1
      GO TO 210
2200  WRITE (6,2210) GS(I),STA(I),HVH
2210  FORMAT (///10X, 4H GS ,F10.2, 7H AT STA,F10.2, 20H IS GREATER THAN
      1HVH,F10.2)
      JCOUNT=1
      IY=I+1
      GO TO 3050
2220  WRITE (6,2210) GS(NL),STA(NL),HVH
      GO TO 9999
2300  WRITE (6,2310)
2310  FORMAT (/// 44H NO. OF PIPE LENGTHS ARE GREATER THAN IPEMAX)
      GO TO 9999
2400  WRITE (6,2410)
2410  FORMAT (/// 41H NO. OF DELIVERIES IS GREATER THAN NDEMAX)
      GO TO 9999
C
C      COMPUTE EARTHWORK, VELOCITY, HEAD CLASS
C      EARTHWORK IS BASED ON USPR DWG. NO. 40-D-6036 MAY 7, 1965
C      PRESSURE PIPE TYPICAL TRENCHES REV. APRIL 20, 1966
C
2900  IF (LA(IS).NE.1) GO TO 3000
      IF (TKWSEL.EQ.0.0) GO TO 3000
      IF (NNI.NE.0) GO TO 3000
      HGL (LASAV)=TKWSEL
      IB=IS+1
      DO 2910 I=IB,LASAV
      NNI=LASAV +1 -I
      HGL(NNI)=HF(NNI) + HGL(NNI+1)
2910  CONTINUE
      ISAV=LASAV-1
      IF (ISAV.EQ.N) GO TO 3000
      GO TO 1000
3000  DO 3040 I=IS,N
      IF (DIA(I).GT.6.0) GO TO 3010
      DIA00(I)=(DIA(I)+2.0)/12.
      TWIDTH(I)=2.0
      GO TO 3040
3010  IF (DIA(I).GT.18.0) GO TO 3020
      DIA00(I)=(DIA(I)+4.0)/12.
      TWIDTH(I)=0.883*(DIA(I)+24.0)
      GO TO 3040
3020  IF (DIA(I).GT.24.0) GO TO 3030
      DIA00(I)=(DIA(I)+4.0)/12.
      TWIDTH(I)=0.883*(DIA(I)+40.0)
      GO TO 3040
3030  DIA00(I)=1.167*DIA(I)/12.
      TWIDTH(I)=0.883*(1.167*DIA(I) +36.0)

```

**** PROGRAM LAKMLP ****

3040 CONTINUE

IY=IS

3050 DO 3100 I=IY,N

NN=NN+1

IF (NN.GT.IPEMAX) GO TO 2300

V(I)=Q(I) / ((3.14159*DIA(I)**2.0) / 576.)

HV(I)=(V(I)*V(I))/64.32

IF (HVH.NE.0.0) GO TO 3070

HVHCK=0.0

IF (I.GE.LASAV) GO TO 3060

HVHCK=1.0

HVH=(HGL(I)+HGL(I+1)) /2.0

GO TO 3070

3060 HVH=TKWSEL + 5.0

3070 IF (GS(I).GT.HVH) GO TO 2200

IW=(HVH-(GS(I)+GS(I+1))/2.0) + DIA00(I)/2.0 +PTPCOV

IF (HVHCK.EQ.0.0) GO TO 3080

HVH=0.0

3080 DUMHC=IW/25

HC(I)=DUMHC * 25.0 + 25.0

MDIA(NN)=DIA(I)

GL(NN)=L(I)

MHC(NN)=HC(I)

EXCAV=TWIDTH(T)*L(I)*((PIPCOV+DIA00(I))/27.)

BKFL=EXCAV-(((3.14159*DIA00(I)**2.0)/4.) *L(I)/27.)

IF (I.EQ.IS) GO TO 3090

SEXCAV(I)=EXCAV+SEXCAV(I-1)

SBKFL(T)=BKFL+SBKFL(I-1)

GO TO 3100

3090 SEXCAV(I)=EXCAV

SBKFL(T)=BKFL

3100 CONTINUE

IF (TKWSEL.EQ.0.0) GO TO 3130

IF (LA(IS).NE.1) GO TO 3110

IF (NL.EQ.LASAV) GO TO 3120

3110 IF (HVH.NE.(TKWSEL+5.)) GO TO 3130

3120 HVH=TKWSEL + 5.0

3130 IF (GS(NL).GT.HVH) GO TO 2220

C

C

SIZE DELIVERIES

C

IR=IS+1

DEL(IS)=0.0

IF (MDEL.EQ.1) GO TO 4170

4000 DO 4160 I=IR,NL

DEL(I)=0.0

IF (LA(IS).NE.1) GO TO 4010

IF (I.EQ.LASAV) GO TO 4160

**** PROGRAM LAKMLP ****

```
4010 IF (I.EQ.NL) GO TO 4020
      IF (LA(I).NE.LA(15)) GO TO 4160
4020 IF (DQ(I).GT.0.0) GO TO 4030
      GO TO 4160
4030 IF (DQ(I).GT.0.02) GO TO 4040
      DEL(I)=1.0
      GO TO 4160
4040 IF (DQ(I).GT.0.05) GO TO 4050
      DEL(I)=1.5
      GO TO 4160
4050 IF (DQ(I).GT.0.178) GO TO 4060
      DEL(I)=2.0
      GO TO 4160
4060 IF (DQ(I).GT.0.446) GO TO 4070
      DEL(I)=3.0
      GO TO 4160
4070 IF (DQ(I).GT.0.891) GO TO 4080
      DEL(I)=4.0
      GO TO 4160
4080 IF (DQ(I).GT.2.025) GO TO 4090
      DEL(I)=6.0
      GO TO 4160
4090 IF (DQ(I).GT.2.674) GO TO 4100
      DEL(I)=8.0
      GO TO 4160
4100 IF (DQ(I).GT.3.555) GO TO 4110
      DEL(I)=10.0
      GO TO 4160
4110 IF (DQ(I).GT.5.013) GO TO 4120
      DEL(I)=12.0
      GO TO 4160
4120 IF (DQ(I).GT.6.684) GO TO 4130
      DEL(I)=14.0
      GO TO 4160
4130 IF (DQ(I).GT.8.457) GO TO 4140
      DEL(I)=16.0
      GO TO 4160
4140 IF (DQ(I).GT.11.227) GO TO 4150
      DEL(I)=18.0
      GO TO 4160
4150 DEL(I)=0.0
4160 CONTINUE
4170 DO 4180 J=18,NL
      IF (DEL(J).EQ.0.0) GO TO 4190
      ND=ND+1
      IF (ND.GT.NDEMAX) GO TO 2400
      SDEL(ND)=DEL(J)
      IF (J.EQ.NL) GO TO 4180
```

**** PROGRAM LAKMLP ****

```

      IF (HC(J).LT.HC(J-1)) GO TO 4180
      JHC(NJ)=HC(J)
      GO TO 4190
4180  JHC(NJ)=HC(J-1)
4190  CONTINUE
      IF (LA(IS).NE.1) GO TO 7000
      C
      C      READ IN COST OF PIPE
7900  REWIND 3
      READ (3,7910) MC1,MC,NC
7910  FORMAT (3I10)
      READ (3,7920) ((C(M,N),M=1,10),N=1,NC)
7920  FORMAT (10F8.2)
      C
      C      MC1 - SMALLEST PIPE DIA. FOR WHICH COST IS GIVEN - HAS TO BE
      C              4,6,OR 8
      C      MC - SUBSCRIPT LIMIT FOR PIPE DIA (MUST BE 10,20,OR 30)
      C      NC - SUBSCRIPT LIMIT FOR PIPE CLASS
      C      C ARRAY IS DIMENSIONED TO PROVIDE FOR DIAMETERS UP TO 120 INCH
      C              AND HEAD UP TO 1000 FT.
      C      COST VALUES SHOULD BE GIVEN FOR HEADS IN INCREMENTS OF 25 FEET
      C
      IF (NC.GT.20) GO TO 7930
      READ (3,7920) ((C(M,N),M=11,MC),N=1,NC)
      GO TO 7000
7930  READ (3,7920) ((C(M,N),M=11,20),N=1,NC)
      READ (3,7920) ((C(M,N),M=21,MC),N=1,NC)
      C
      C
7000  N=NL-1
      RMC1=MC1
      DO 8100 J=IS,N
      IF (L(J).EQ.0.0) GO TO 8100
      IRC=IRC+1
      IC=IC+1
      HCC(IC)=HC(J)
      HCC(IC+1)=HC(J)
      HCC(IC+2)=HC(J)
      HCC(IC+3)=HC(J)
      HCC(IC+4)=HC(J)
      VH=(HC(J)+.1)/25.
      IR(J) =IRC
      IF (DIA(J).GT.12.) GO TO 7010
      ID=DIA(J)/25.-1.
      GO TO 7030
7010  IF (DIA(J).GT.54.) GO TO 7020
      ID=DIA(J)/25. + 1.
      GO TO 7030

```

**** PROGRAM LAKMLP ****

```

7020 ID=OIA(J)/5. + 10.
7030 IF ((ID-IP).GT.2) GO TO 7050
7040 DP(IC ) =PIPARR(IP+4)
      DP(IC+1) =PIPARR(IP+3)
      DP(IC+2) =PIPARR(IP+2)
      DP(IC+3) =PIPARR(IP+1)
      DP(IC+4) =PIPARR(IP)
      GO TO 7070
7050 IF (ID.GE.28) GO TO 7060
      DP(IC ) =PIPARR(ID+2)
      DP(IC+1) =PIPARR(ID+1)
      DP(IC+2) =OIA(J)
      DP(IC+3) =PIPARR(ID-1)
      DP(IC+4) =PIPARR(ID-2)
      GO TO 7070
7060 DP(IC ) =PIPARR(30)
      DP(IC+1) =PIPARR(29)
      DP(IC+2) =PIPARR(28)
      DP(IC+3) =PIPARR(27)
      DP(IC+4) =PIPARR(26)
7070 IC4=IC+4
      DO 8080 I=IC,IC4
      VP(I)=Q(J) / ((3.14159*DP(I)*DP(I)) / 575.)
      IF (DP(I).GT.22.) GO TO 7080
      CS=CA
      GO TO 7090
7080 CS=CB
7090 HP(I)=(331.775 * Q(J)*Q(J)) / (CS * CS * DP(I)**5.25)
      HVP(I)=(VP(I)*VP(I)) / 64.32
C
C      LOOK UP COST OF PIPE
C
      IF (DP(I).LE.10.) GO TO 8020
      IF (DP(I).LE.54.) GO TO 8010
      M=DP(I)/5. + 12.2 -(RMC1/2.)
      GO TO 8030
8010 M=DP(I)/3. + 3.2 -(RMC1/2.)
      GO TO 8030
8020 M=DP(I)/2. + 1.2 -(RMC1/2.)
8030 IF (NH.LE.NC) GO TO 8050
      WRITE (6,8040) DP(I),NH
8040 FORMAT (// * HEAD CLASS FOR PIPE *,F5.0,* IN. MUST BE *,F5.0)
      DNENTR=1.0
8050 IF (M.LE.NC) GO TO 8070
      WRITE (6,8060) DP(I)
8060 FORMAT (// * PIPE DECK COST MUST INCLUDE COST FOR *,F5.0,*IN.PIPE*)
      DNENTR=1.0
8070 COSTPI(I)=C(M,NH)

```

**** PROGRAM LAKMLP ****

```

8080  CONTINUE
      IC=IC+4
8100  CONTINUE
C
C      WRITE FINAL ANSWERS
5000  DO 5090 I=IS,N
      IF (AC(I).EQ.0.0) GO TO 5040
      IF (I.EQ.IS) GO TO 5040
      IF (LA(I).NE.LA(IS)) GO TO 5020
      WRITE (JW,5010) STA(I),HGL(I),AC(I),DQ(I),DEL(I),HGR(I),GS(I)
5010  FORMAT (1X,F10.2,3X,F8.2,41X,20X,F9.2,6X,F5.2,F5.1,F8.2,F3.2)
      GO TO 5060
5020  WRITE (JW,5030) STA(I),HGL(I),(LAT(I,II),II=1,2),AC(I),HGR(I),GS(I)
5030  FORMAT (1X,F10.2,3X,F8.2,41X,2A10,F9.2,17X,,F8.2,F8.2)
      GO TO 5060
5040  WRITE (JW,5050) STA(I),HGL(I),GS(I)
5050  FORMAT (1X,F10.2,3X,F8.2,95X,F8.2)
5060  WRITE (JW,5070) Q(I),DIA(I),V(I),HV(I),H(I),L(I),HF(I),SAC(I),HC(I)
5070  FORMAT (13X,F7.2,6X,F5.0,2F6.2,F9.6,F12.2,F7.2,24X,F10.2,26X,F5.0)
      IF (EQ(I).EQ.0.0) GO TO 5090
      WRITE (JW,5080) EQ(I)
5080  FORMAT (1H+,3HEQ=,F9.2)
5090  CONTINUE
6490  WRITE (7,6500) IS,N
6500  FORMAT (2I5)
      DO 6516 I=IS,N
      WRITE (7,6510) LA(I),STA(I),(LAT(I,II),II=1,2),AC(I),EQ(I),DQ(I),
1 DEL(I),HGR(I),GS(I),Q(I),L(I),SAC(I),HC(I)
6510  FORMAT (I5,F10.2,2A10,2F9.2,F6.2,F5.1,2F8.2,F10.5,2F10.2,F5.0)
      IF (L(I).EQ.0.0) GO TO 6516
      IL=IL+1
      IL4=IL+4
      WRITE (7,6514) (DP(II),II=IL,IL4)
6514  FORMAT (5F10.2)
      IL=IL+4
6516  CONTINUE
      WRITE (7,6520) NL
6520  FORMAT (I5)
      WRITE (7,6515) LA(NL),STA(NL),AC(NL),DQ(NL),DEL(NL),HGR(NL),GS(NL)
6515  FORMAT (I5,F10.2,20X,F9.2,F5.2,F5.1,2F8.2)
      IF (DEL(NL).EQ.0.0) GO TO 6000
      WRITE (JW,6010) STA(NL),HGL(NL),AC(NL),DQ(NL),DEL(NL),HGR(NL),GS(NL)
      GO TO 9999
6000  WRITE (JW,6010) STA(NL),HGL(NL),AC(NL),HGR(NL),GS(NL)
6010  FORMAT (1X,F10.2,3X,F8.2,41X,20X,F9.2,17X,2F8.2)
9999  RETURN
      END

```

**** INPUT FILE DATA1 ****

	1.5	4.5	0.	1.53	7.1	.345	.370	6.
	9		1	7.684		1100.	1110.	
MAIN								
	1		0.	0.	0.	1110.		
	1	1500.		110.	1090.	1089.		
	2	2900.		0.	0.	1078.		
SUB 1								
	2	0.		0.	0.	1078.		
	3	400.		0.	0.	1079.		
SUB 1-A								
	3	0.		0.	0.	1079.		
	0	600.		110.	1032.	1079.		
	0	1000.		90.	1035.	1083.		
	1	2900.		75.	1080.	1077.		
	2	4250.		0.	0.	1071.		
SUB 2								
	2	0.		0.	0.	1071.	-250.	
	0	1050.		80.	1075.	1073.		
	0	5850.		100.	1060.	1058.		
	8							

**** INPUT FILE PIPRIC ****

PIPE SIZES 4 INCHES THROUGH 27 INCHES

4	30	20	EXAMPLE	PROJECT	PIPE PRICES			DEC.1973	
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.70	16.38	19.10
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.70	16.38	19.60
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.70	16.38	20.10
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.70	16.38	21.10
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.70	16.38	21.60
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.70	16.38	22.10
2.68	3.65	4.65	5.73	6.77	8.31	10.45	13.75	16.38	25.60
2.68	3.65	4.65	5.73	6.77	8.31	10.45	14.20	16.88	25.60
2.68	3.65	4.65	5.73	6.77	8.81	11.05	14.20	16.88	25.60
2.68	3.65	4.65	5.73	6.77	8.81	11.05	14.20	16.88	25.60
2.68	3.65	4.65	5.73	6.77	8.81	12.95	16.70	20.38	26.60
2.68	3.65	4.65	5.93	7.07	9.91	12.95	16.70	20.38	26.60
2.68	3.65	4.85	5.93	7.07	9.91	12.95	16.70	20.38	26.60
2.68	3.65	4.85	6.43	7.77	10.21	13.45	17.20	21.38	26.60
2.68	3.65	5.05	6.43	7.77	10.21	13.45	17.20	21.38	27.60
2.68	3.65	5.05	6.73	8.17	10.81	13.95	18.20	22.38	27.60
2.83	3.85	5.35	6.73	8.17	10.81	13.95	18.20	22.38	27.60
2.83	3.85	5.35	6.73	9.47	12.81	16.45	21.20	26.38	27.60
2.83	4.05	5.75	7.53	9.47	12.81	16.45	21.70	26.38	28.60
2.83	4.05	5.75	7.53	9.47	12.81	16.45	21.70	26.38	28.60

*** INPUT FILE PIPRIC ***

PIPE SIZES 30 INCHES THROUGH 57 INCHES

1.82	24.06	27.29	30.54	33.80	36.07	40.34	43.62	46.92	55.52
2.32	25.06	28.29	31.54	34.80	38.07	42.34	45.62	49.92	58.52
2.82	26.06	29.29	32.54	36.80	40.07	44.34	47.62	51.92	61.52
3.82	27.06	30.29	34.54	37.80	42.07	46.34	50.62	54.92	64.52
4.82	28.06	31.29	35.54	39.80	44.07	48.34	52.62	57.92	67.52
5.82	28.06	33.29	36.54	40.80	45.07	50.34	54.62	59.92	70.52
8.82	33.06	37.29	40.54	45.80	50.07	54.34	59.62	63.92	74.52
8.82	33.06	37.29	41.54	45.80	50.07	55.34	59.62	64.92	76.52
9.82	33.06	37.29	41.54	46.80	51.07	56.34	61.62	66.92	77.52
9.82	34.06	38.29	42.54	46.80	52.07	57.34	62.62	67.92	79.52
9.82	34.06	38.29	43.54	47.80	53.07	58.34	63.62	68.92	80.52
9.82	34.06	39.29	43.54	48.80	53.07	58.34	64.62	69.92	82.52
0.82	35.06	39.29	43.54	48.80	54.07	59.34	64.62	70.92	83.52
0.82	35.06	39.29	44.54	48.80	54.07	60.34	65.62	71.92	84.52
1.82	36.06	40.29	45.54	50.80	56.07	61.34	67.62	73.92	87.52
1.82	36.06	41.29	45.54	50.80	57.07	62.34	68.62	74.92	88.52
2.82	37.06	42.29	46.54	51.80	58.07	63.34	69.62	75.92	89.52
2.82	38.06	43.29	47.54	52.80	59.07	64.34	69.62	76.92	90.52
3.82	39.06	44.29	47.54	53.80	59.07	65.34	70.62	77.92	92.52
3.82	40.06	46.29	48.54	54.80	60.07	67.34	71.62	78.92	94.52

**** SUBROUTINE SUBSAC ****

SUBROUTINE SACR (NS,SAC,AC,Q,DO,NF)
DIMENSION SAC(1),AC(1),Q(1),DQ(1)

C
C
C

EXAMPLE PROJECT Q=6.1 GPM/AC 11-29-73

DO 500 I=NS,NF
Q(I)=SAC(I) *0.0136
500 CONTINUE
NF1=NF+1
DO 600 I=NS,NF1
DQ(I)=AC(I) *0.0136
600 CONTINUE
RETURN
END

DYNAMIC PROGRAMMING SOLUTION
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY										MAIN		75/04/13.							
STATION	Q	HGL	DIA	V	HW	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	PIPE CLASS DESIGN ELEVATION = 1110.00		AC	SAC	DQ	DEL	HGR	NGS	HC	
										AC	HC								
0.00		1100.00	21.	3.19	.16	.001907	1500.00	2.86											
1500.00	7.68	1097.14	19.	3.50	.19	.002779	1400.00	3.89				110.00	565.00	1.50	6.0	1090.00	1069.00	25.	
2900.00	6.19	1093.25	10.	6.36	.63	.019101	0.00	0.00	SUB 1			200.00	455.00			1089.73	1078.00	50.	
2900.00	3.47	1093.25	10.	6.36	.63	.019101	0.00	0.00				75.00	255.00	1.02	6.0	1080.00	1077.00	50.	
4250.00	2.45	1080.40	10.	4.49	.31	.009518	1350.00	12.85				80.00	180.00			1078.00	1071.00	50.	
5850.00	1.36	1065.23	9.	3.90	.24	.009479	1600.00	15.17	SUB 2			100.00	100.00	1.36	6.0	1060.00	1058.00	75.	

DYNAMIC PROGRAMMING SOLUTION
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY

SUB 1

PIPE CLASS DESIGN ELEVATION = 1110.00

STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
0.00		1091.75	12.	3.46	.19	.004512	400.00	1.80							1078.00	50.
400.00	2.72	1089.94							SUB 1-A	110.00	200.00			1084.32	1079.00	50.
1000.00	1.22	1085.34	8.	3.51	.19	.007678	600.00	4.61		90.00	90.00	1.22	6.0	1085.00	1085.00	50.

75/04/13.

DYNAMIC PROGRAMMING SOLUTION
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY																
SUB 1-A																
PIPE CLASS DESIGN ELEVATION = 1110.00																
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
0.00		1088.44	10.	2.74	.12	.003554	600.00	2.13		110.00	110.00	1.50	6.0	1082.00	1079.00	50.
600.00	1.50	1086.31								110.00	110.00	1.50	6.0	1082.00	1078.00	

75/04/13.

DYNAMIC PROGRAMMING SOLUTION
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY																
SUB 2																
PIPE CLASS DESIGN ELEVATION = 1110.00																
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
EQ =																
0.00		1078.90													1071.00	
-250.00	1.09		10.	1.99	.06	.001880	800.00	1.50		80.00	80.00	1.09	6.0	1075.00	1073.00	50.
1050.00		1077.40														

75/04/13.

**** PROGRAM LPFTN ****

```
PROGRAM ZLPANS(LPANS,FTANS,TAPE12=LPANS,TAPE8=FTANS)
DIMENSION WORD(7)
EQUIVALENCE(WORD(1),IWORD)
READ(12) X,(WORD(K),K=1,7)
WRITE (8,100) WORD(7)
100 FORMAT ( 1X,F15.2 )
110 READ (12) X,(WORD(K),K=1,7)
IF (IWORD.NE. 3HX11) GO TO 110
GO TO 125
120 READ (12) X,(WORD(K),K=1,7)
125 IF (IWORD.EQ. 2HF1) GO TO 999
IF (IWORD.EQ.7H$BEND$B) GO TO 999
WRITE (8,130) WORD(1),WORD(2)
130 FORMAT (1X,A10,F10.2)
GO TO 120
999 CALL EXIT
END
```

**** PROGRAM LEQANS ****

```

PROGRAM REPORT (ANS,FTANS,OUTPUT,INFILE,TAPE8=FTANS,
1 TAPE7=ANS,TAPE6=OUTPUT,TAPE10=INFILE,TAPE9)
C**** PROGRAM READS FROM TWO TAPES TO GENERATE A FINAL REPORT
C**** ANS - FILE CREATED BY LAKMLP
C**** FTANS - FILE CREATED BY LPFTN
C****
COMMON HYDUM,TEELOS,IVALVE,IDUM
DIMENSION LA1( 50),STA1( 50),HGL1( 50),LAT1(3),HV1( 50),
2 LA2(125),STA2(125),HGL2(125),LAT2(50,2),HV2(125),
3 LA3(230),STA3(230),HGL3(230),LAT3(125,2),HV3(230),
4 LA4(175),STA4(175),HGL4(175),LAT4(230,2),HV4(175),
5 LA5( 75),STA5( 75),HGL5( 75),LAT5(175,2),HV5( 75),
6 WHGR1( 50),WHGR2(125),WHGR3(230),WHGR4(175),WHGR5( 75),
7 DEL1( 50),DEL2(125),DEL3(230),DEL4(175),DEL5( 75),
8 AC1( 50),AC2(125),AC3(230),AC4(175),AC5( 75),
9 HGR1( 50),HGR2(125),HGR3(230),HGR4(175),HGR5( 75),
1 GS1( 50),GS2(125),GS3(230),GS4(175),GS5( 75),
2 EQ1( 50),EQ2(125),EQ3(230),EQ4(175),EQ5( 75)
DIMENSION TODAY(2),TLOSS(50)
CALL DAMOYR(TODAY)
ISP=0
HYDUM=0.0
READ (7,100) (LAT1(II),II=1,3),ITYPE,STAINIL,TEELOS,AVH1
100 FORMAT (3A10,I10,3F10.2)
WRITE (6,110) (LAT1(II),II=1,3),TODAY
110 FORMAT (1H1,35H ECONOMICAL PIPE HYDRAULIC STUDY,25X,3A10,25X,
1 2A10//)
GO TO (120,120,150,150),ITYPE
120 READ (7,130) HVP,IDUM
130 FORMAT (F10.2,I10)
WRITE (6,140) HVP
140 FORMAT (48X,30H PIPE CLASS DESIGN ELEVATION =,F10.2/)
GO TO 170
150 WRITE (6,160)
160 FORMAT(38X,50H PIPE CLASS DESIGN ELEVATION = HYDRAULIC GRADE LINE//)
READ (7,165) IDUM
165 FORMAT (I11)
170 GO TO (270,250,190,210),ITYPE
180 READ (7,190) TKWSEL,STASAV
190 FORMAT (2F10.2)
WRITE (6,200) TKWSEL,STASAV
200 FORMAT (28X,39H DOWN TO THE KNOWN TANK WATER SURFACE (,F10.2,
1 9H ) AT STA,F10.2/)
GO TO 230
210 READ (7,190) TKWSEL,STASAV
WRITE (6,220) TKWSEL,STASAV
220 FORMAT (26X,42H DOWN TO THE COMPUTED TANK WATER SURFACE (,F10.2,
1 9H ) AT STA,F10.2/)

```

**** PROGRAM LEQANS ****

```

230 IF (STASAV.EQ.STA1NIL) GO TO 270
    WRITE (6,240) STASAV,TKWSEL
240 FORMAT (25X,10H AFTER STA,F10.2,36H ,THE PIPE CLASS DESIGN ELEVATI
    10N = ,F10.2, 10H + 5.0 FT./)
    GO TO 270
250 WRITE (6,260) AVH1
260 FORMAT (28X,10H WATER SURFACE IS (,F10.2,37H ) IN THE TANK NEAR TH
    1E PUMPING PLANT/)
270 WRITE (6,280)
280 FORMAT (* STATION          Q      HGL      DIA      V      HV      SLOPE
    1 LENGTH      LOSS      SUBLATERAL NAME      AC      SAC      DO      DEL      HGR
    2 NGS          HC*///)
C
C**** WRITE MAIN LATERAL
C
    READ (8,300) TOTANS
300 FORMAT (1X,F15.2)
C**** IF (ITYPE.GT.2) GO TO 305
305 CALL WRIANS (LA1,STA1,HGL1,HV1,50,AVH1,I1,N1,SULOSS1,WHGR1)
C**** WRITE (6,306) (WHGR1(I),I=1,N1)
C*06 FORMAT (1X,F8.2,/)
    N1=N1+1
    I=0
310 I=I+1
    IF (I.GE.N1) GO TO 8000
    IF (LA1(I).NE.2) GO TO 310
C**** WRITE SUBS
    READ (7,320) (LAT2(I,II),II=1,2),IVALVE
320 FORMAT (2A10,I10)
    WRITE (6,330) (LAT2(I,II),II=1,2),TODAY
330 FORMAT (1H1,35H ECONOMICAL PIPE HYDRAULIC STUDY,30X,2A10,30X,
    1 2A10//)
    GO TO (340,340,350,350),ITYPE
340 AVH2=HGL1(T)
    HYDUM=HV1(I-1)
    GO TO 370
350 IF (STA1(I).GT.STASAV) GO TO 360
    AVH2=TKWSEL
    GO TO 370
360 AVH2=HGL1(T)
    HYDUM=HV1(I-1)
370 READ (7,130) HVH
    WRITE (6,140) HVH
    WRITE (6,280)
    CALL WRIANS (LA2,STA2,HGL2,HV2,125,AVH2,I2,N2,SULOSS2,WHGR2)
C**** WRITE (6,306) (WHGR2(J),J=I2,N2)
    ISP = ISP + 1
    TLOSS(TSP) = SULOSS2

```

**** PROGRAM LEQANS ****

```

*****WRITE (6,371) I2,N2
*71  FORMAT (2I10)
      N2=N2+1
      JB=0
380  J=JB+I2
      JB=JB+1
*****WRITE(6,381)J,LA2(J),STA2(J),HGL2(J)
*81  FORMAT (2I10,2F10.2)
      IF (J.GE.N2) GO TO 310
      IF (LA2(J).NE.3) GO TO 380
      READ (7,320) (LAT3(J,II),II=1,2),IVALVE
      WRITE (6,330) (LAT3(J,II),II=1,2),TODAY
      READ (7,130) HVH
      WRITE (6,140) HVH
      WRITE (6,280)
      HVDUM=HV2(J-1)
      AVH3=HGL2(J)
      CALL WRIANS (LA3,STA3,HGL3,HV3,230,AVH3,I3,N3,SULOSS3,WHGR3)
C**** WRITE (6,306) (WHGR3(K),K=I3,N3)
      ISP = ISP + 1
      TLOSS(ISP) = SULOSS3
      N3=N3+1
      KB=0
390  K=KB+I3
      KB=KB+1
      IF (K.GE.N3) GO TO 380
      IF (LA3(K).NE.4) GO TO 390
      READ (7,320) (LAT4(K,II),II=1,2),IVALVE
      WRITE (6,330) (LAT4(K,II),II=1,2),TODAY
      READ (7,130) HVH
      WRITE (6,140) HVH
      WRITE (6,280)
      HVDUM=HV3(K-1)
      AVH4=HGL3(K)
      CALL WRIANS (LA4,STA4,HGL4,HV4,175,AVH4,I4,N4,SULOSS4,WHGR4)
      ISP =ISP + 1
      TLOSS(ISP) = SULOSS4
      N4=N4+1
      LB=0
400  L=LB+I4
      LB=LB+1
      IF (L.GE.N4) GO TO 390
      IF (LA4(L).NE.5) GO TO 400
      READ (7,320) (LAT5(L,II),II=1,2),IVALVE
      WRITE (6,330) (LAT5(L,II),II=1,2),TODAY
      READ (7,130) HVH
      WRITE (6,140) HVH
      WRITE (6,280)

```

**** PROGRAM LEQANS ****

```

AVDUM=HV4(L-1)
AVH5=HGL4(L)
CALL WPIANS (LA5, STA5, HGL5, HV5, 75, AVH5, I5, N5, SULOSS5, WHGR5)
ISP=ISP+1
TLOSS(ISP)=SULOSS5
N5=N5+1
GO TO 400
8000 WRITE (6,7999) TOTANS
7999 FORMAT (///10X,*TOTAL COST OF PIPE IS $*,F15.2)
C**** WRITE (6,425) (TLOSS(IRQ),IRQ=1,ISP)
C*25 FORMAT (1X,F8.2,/)
READ (10,430) TLELOS,PIPCOV,DWSADD,X,Y,CSS,CS3,PIPMIN,IPCOST
430 FORMAT (2F5.2,3F10.2,2F10.3,F10.2,I10)
EOADD = DWSADD
DWSADD = 0.0
WRITE (9,430) TLELOS,PIPCOV,DWSADD,X,Y,CSS,CS3,PIPMIN,IPCOST
READ (10,435) MDEL,SENTRY,ITYPE,TQP,CP,AVH1,HVH1,TKWSEL,GDIFF,
1 INPUT
435 FORMAT (2I5,I10,5F10.2,F5.2,I5)
WRITE (9,435) MDEL,SENTRY,ITYPE,TQP,CP,AVH1,HVH1,TKWSEL,GDIFF,
1 INPUT
READ (10,440) (LAT1(II),II=1,3)
440 FORMAT (3A10,I10)
WRITE (9,440) (LAT1(II),II=1,3),IDUM
J1=0
I=0
J=0
K=0
L=0
M=0
445 I=I+1
READ(10,450) DEL1(I),LA1(I),STA1(I),AC1(I),HGR1(I),GS1(I),EQ1(I)
450 FORMAT (F5.2,I5,5F10.2)
IF (I.EQ.1) GO TO 455
IF (ITYPE.LE.2) GO TO 452
IF (STA1(I).EQ.STASAV) WHGR1(I)=0.99
452 IF (LA1(I).EQ.1) GO TO 460
IF (LA1(I).EQ.2) GO TO 465
HGR1(I) = HGR1(I) + EOADD
WRITE (9,450) DEL1(I),LA1(I),STA1(I),AC1(I),HGR1(I),GS1(I),EQ1(I)
GO TO 455
455 WRITE (9,450) DEL1(I),LA1(I),STA1(I),AC1(I),HGR1(I),GS1(I),EQ1(I)
GO TO 445
460 WRITE (9,450) DEL1(I),LA1(I),STA1(I),AC1(I),WHGR1(I),GS1(I),EQ1(I)
GO TO 445
465 WRITE (9,450) DEL1(I),LA1(I),STA1(I),AC1(I),HGR1(I),GS1(I),EQ1(I)
READ (10,470) (LAT2(I,II),II=1,2),IVALVF
470 FORMAT (2A10,I10)

```

**** PROGRAM LEGANS ****

```

      J1 = J1+1
      WRITE (9,475) (LAT2(I,II),II=1,2),IVALVE,TLOSS(J1),TLOSS(J1)
475  FORMAT (2A1',I1',2F3.2)
      TSAV2=TLOSS(J1)
      JJ = J+1
480  J = J+1
      READ (10,450) DEL2(J),LA2(J),STA2(J),AC2(J),HGR2(J),GS2(J),EQ2(J)
      IF (J.EQ.JJ) GO TO 435
      IF (LA2(J).EQ.2) GO TO 490
      IF (LA2(J).EQ.3) GO TO 495
      HGR2(J) = HGR2(J) + EOADD
      WRITE (9,450) DEL2(J),LA2(J),STA2(J),AC2(J),HGR2(J),GS2(J),EQ2(J)
      GO TO 445
485  WRITE (9,450) DEL2(J),LA2(J),STA2(J),AC2(J),HGR2(J),GS2(J),EQ2(J)
      GO TO 480
490  WRITE (9,450) DEL2(J),LA2(J),STA2(J),AC2(J),WHGR2(J),GS2(J),EQ2(J)
      GO TO 480
495  WRITE (9,450) DEL2(J),LA2(J),STA2(J),AC2(J),HGR2(J),GS2(J),EQ2(J)
      READ (10,470) (LAT3(J,II),II=1,2),IVALVE
      J1 = J1+1
      TLOSS(J1)=TLOSS(J1)+TSAV2
      TSAV=TLOSS(J1)-TSAV2
      WRITE (9,475) (LAT3(J,II),II=1,2),IVALVE,TLOSS(J1),TSAV
      TSAV3=TLOSS(J1)
      KK = K+1
500  K = K+1
      READ (10,450) DEL3(K),LA3(K),STA3(K),AC3(K),HGR3(K),GS3(K),EQ3(K)
      IF (K.EQ.KK) GO TO 505
      IF (LA3(K).EQ.3) GO TO 510
      IF (LA3(K).EQ.4) GO TO 515
      HGR3(K) = HGR3(K) + EOADD
      WRITE (9,450) DEL3(K),LA3(K),STA3(K),AC3(K),HGR3(K),GS3(K),EQ3(K)
      GO TO 480
505  WRITE (9,450) DEL3(K),LA3(K),STA3(K),AC3(K),HGR3(K),GS3(K),EQ3(K)
      GO TO 500
51  WRITE (9,450) DEL3(K),LA3(K),STA3(K),AC3(K),WHGR3(K),GS3(K),EQ3(K)
      GO TO 500
515  WRITE (9,450) DEL3(K),LA3(K),STA3(K),AC3(K),HGR3(K),GS3(K),EQ3(K)
      READ (10,470) (LAT4(K,II),II=1,2),IVALVE
      J1 = J1+1
      TLOSS(J1)=TLOSS(J1)+TSAV3
      TSAV=TLOSS(J1)-TSAV3
      WRITE (9,475) (LAT4(K,II),II=1,2),IVALVE,TLOSS(J1),TSAV
      TSAV4=TLOSS(J1)
      LL = L+1
520  L = L+1
      READ (10,450) DEL4(L),LA4(L),STA4(L),AC4(L),HGR4(L),GS4(L),EQ4(L)
      IF (L.EQ.LL) GO TO 525

```

**** PROGRAM LEOANS ****

```

IF (LA4(L).EQ.4) GO TO 530
IF (LA4(L).EQ.5) GO TO 535
HGR4(L) = HGR4(L) + EOADD
WRITE (9,450) DEL4(L),LA4(L),STA4(L),AC4(L),HGR4(L),GS4(L),EQ4(L)
GO TO 500
525 WRITE (9,450) DEL4(L),LA4(L),STA4(L),AC4(L),HGR4(L),GS4(L),EQ4(L)
GO TO 520
530 WRITE (9,450) DEL4(L),LA4(L),STA4(L),AC4(L),WHGR4(L),GS4(L),EQ4(L)
GO TO 520
535 WRITE (9,450) DEL4(L),LA4(L),STA4(L),AC4(L),HGR4(L),GS4(L),EQ4(L)
READ (10,470) (LAT5(L,II),II=1,2),IVALVF
J1 = J1+1
TLOSS(J1)=TLOSS(J1)+TSAV4
TSAV=TLOSS(J1)-TSAV4
WRITE (9,475) (LAT5(L,II),II=1,2),IVALVF,TLOSS(J1),TSAV
MM = M+1
540 M = M+1
READ (10,450) DEL5(M),LA5(M),STA5(M),AC5(M),HGR5(M),GS5(M),EQ5(M)
IF (M.EQ.MM) GO TO 545
IF (LA5(M).EQ.5) GO TO 550
HGR5(M) = HGR5(M) + EOADD
WRITE (9,450) DEL5(M),LA5(M),STA5(M),AC5(M),HGR5(M),GS5(M),EQ5(M)
GO TO 520
545 WRITE (9,450) DEL5(M),LA5(M),STA5(M),AC5(M),HGR5(M),GS5(M),EQ5(M)
GO TO 540
550 WRITE (9,450) DEL5(M),LA5(M),STA5(M),AC5(M),WHGR5(M),GS5(M),EQ5(M)
GO TO 540
555 WRITE (9,556)
556 FORMAT (*      */*      *)
REWIIND 9
CALL REPPLAC (5HTAPE9,6HOUTFIL)
CALL EXIT
END
SUBROUTINE WRIANS (LA,STA,HGL,HV,IO,AVH,IS,NSAV,SULOSS,WHGF)
COMMON HVDUM,FEELDS,IVALVF,IDUM
DIMENSION LAD(300),STAD(300),LATD(300,2),ACD(300),EQD(300),
1          DQD(300),DELD(300),HGRD(300),GSD(300),DD(300),LD(300),
2          SACD(300),HCD(300),
3          DP(300,5),LR(300,5),LRJ(300,5),DPJ(300,5)
DIMENSION LA(ID),STA(ID),HGL(ID),HV(ID),WHGR(ID)
DIMENSION LAT(300,2),AC(300),DQ(300),DEL(300),HGR(300),GS(300),
1          Q(300),D(300),V(300),H(300),L(300),HF(300),
2          SAC(300),HC(300),EQ(300)
REAL L,LD,LRJ,LR
UNDER1=74047404740474048
UNDER2=7404740474043

```

C
C**** READ THE TWO INPUT FILES

**** PROGRAM LEOANS ****

C

```

100 READ (7,100) IS,N
    FORMAT (2I5)
    DO 150 I=IS,N
      READ (7,110) LAD(I),STAD(I),(LATD(I,II),II=1,2),ACD(I),EQD(I),
1      DGD(I),DELD(I),HGRD(I),GSD(I),QD(I),LD(I),SACD(I),HCD(I)
110  FORMAT (I5,F10.2,2A10,2F9.2,F6.2,F5.1,2F8.2,F10.5,2F1 .2,F5.4)
      IF (LD(I).EQ.0.0) GO TO 150
      READ (7,120) (DP(I,II),II=1,5)
120  FORMAT (5F10.2)
      DO 140 J=1,5
      READ (8,130) LR(I,J)
130  FORMAT (11X,F10.2)
140  CONTINUE
150  CONTINUE
      READ (7,160) NL
160  FORMAT (I5)
      READ (7,170) LAD(NL),STAD(NL),ACD(NL),DGD(NL),DELD(NL),HGRD(NL),
1      GSD(NL)
170  FORMAT (I5,F10.2,20X,F9.2,F6.2,F5.1,2F8.2)

```

C

C**** ADD TWO ARRAYS TO FORM ONE (NEW SUBSCRIPTS)

C

```

      NSAV=N
      IC=IS
180  DO 240 I=IS,N
      IF (LD(I).NE.0.0) GO TO 185
      JCON=1
      L(IC)=0.0
      GO TO 210
185  JCON=0
      DO 190 J=1,5
      IF (LR(I,J).EQ.0.0) GO TO 190
      JCON=JCON + 1
      LRJ(I,JCON) = LR(I,J)
      DPJ(I,JCON) = DP(I,J)
190  CONTINUE
200  LA(IC)=LAD(I)
      STA(IC)=STAD(I)
      LAT(IC,1)=LATD(I,1)
      LAT(IC,2)=LATD(I,2)
      AG(IC)=ACD(I)
      EQ(IC)=EQD(I)
      DJ(IC)=DGD(I)
      DEL(IC)=DELD(I)
      HGR(IC)=HGRD(I)
      GS(IC)=GSD(I)
      Q(IC)=QD(I)

```

**** PROGRAM LEQANS ****

```

SAC(IC)=SACD(I)
HS(IC)=HSD(I)
IF (L(I).EQ.0.0) GO TO 230
GO TO (201,202,203,203),JCON
201 D(IC)=DPJ(I,1)
L(IC)=LRJ(I,1)
GO TO 222
202 D(IC)=DPJ(I,1)
LA(IC+1)=LAD(I)
D(IC+1)=DPJ(I,2)
STA(IC+1)=STA(IC) + LRJ(I,1)
Q(IC+1)=QD(I)
AC(IC+1)=0.0
EQ(IC+1)=EQ(IC)
EQ(IC)=0.0
SAC(IC+1)=SACD(I)
GS(IC+1)=1.0
HCB=HCD(I)
HCA=HCD(I+1)
HS(IC+1)=AMAX1(HCB,HCA)
L(IC)=LRJ(I,1)
L(IC+1)=LRJ(I,2)
GO TO 210
203 WRITE (6,204)
204 FORMAT (1H1,* E R R O R - ADD MORE STATEMENTS AT 203 *)
CALL EXIT
210 J=I+1
IG=IC+JCON
DO 220 M=J,N
LA(IG)=LAD(M)
STA(IG)=STAD(M)
LAT(IG,1)=LATD(M,1)
LAT(IG,2)=LATD(M,2)
AC(IG)=ACD(M)
EQ(IG)=EQD(M)
DQ(IG)=DQD(M)
DEL(IG)=DEL(M)
HGR(IG)=HGRD(M)
GS(IG)=GSD(M)
Q(IG)=QD(M)
SAC(IG)=SACD(M)
HC(IG)=HCD(M)
IG=IG+1
220 CONTINUE
NSAV=NSAV+JCON-1
222 NSVL=NSAV+1
LA(NSVL)=LAD(NL)
STA(NSVL)=STAD(NL)

```

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**** PROGRAM LEQANS ****

```

AC(NSVL)=ACB(NL)
JQ(NSVL)=JQB(NL)
DEL(NSVL)=DELD(NL)
HGR(NSVL)=HGRD(NL)
GS(NSVL)=GSD(NL)
230 IC=IC+JQCN
240 CONTINUE
CSS=.345
CSB=.370
C
C**** COMPUTE PIPE HYDRAULIC PROPERTIES
C
1000 DO 1030 I=TS,NSAV
      HF(I)=0.0
      IF (L(I).EQ.0.0) GO TO 1025
      V(I)=Q(I) / ((3.14159*D(I)*D(I)) /576.)
      IF (D(I).GT.22.) GO TO 1010
      CS=3.14159*CSS
      GO TO 1020
1010 CS=3.14159*CSB
1020 H(I)=(331.776*Q(I)*Q(I)) / (CS*CS*D(I)**5.25)
      HV(I)=(V(I)*V(I)) /64.32
      HF(I)=H(I)*L(I)
      GO TO 1030
1025 HV(I)=HV(I-1)
1030 CONTINUE
C
C**** COMPUTE HYDRAULIC GRADE LINE
C
      IF (LA(IS).EQ.1) GO TO 4098
      IF (IVALVE.EQ.0) GO TO 4000
      TRULS=1.25*HV(TS)
      WRITE (6,1060) AVH,HVDUM,TRULS
1060 FORMAT(1X*AVAILABLE HEAD =*7X,F8.2/1X*VELOCITY HEAD =*8X,F8.2
1/1X*TEE LOSS =*13X,F8.2)
      SULOSS=HVDUM+TRULS
      GO TO 4999
4000 IF (D(IS).LE.12.) GO TO 4005
      IF (V(IS).LT.10.0) GO TO 4020
4005 TRULS = 1.25 * HV(IS)
      VRULS = .4 * HV(IS)
      WRITE (6,4010) AVH,HVDUM,TRULS,D(IS),VRULS
4010 FORMAT (1X*AVAILABLE HEAD =*7X,F8.2
1/1X*VELOCITY HEAD =*8X,F8.2
1/1X*TEE LOSS =*13X,F8.2
1/1X,F8.0* INCH VALVE LOSS =*2X,F8.2 )
      TPLS2=0.0
      GO TO 4998

```

**** PROGRAM LEGANS ****

```

4020 VSAVE = V(IS)
      DSAVE = D(IS)
      IK = 10
      IL = 20
      IM = 2
4030 DO 4050 I=IK,IL,IM
      DTEST = D
      VTEST = Q(IS)/(3.14159*DTEST*DTEST)/576.)
      IF (VTEST.LT.VSAVE.OR.VTEST.GT.10.0) GO TO 4040
      VSAVE = VTEST
      DSAVE = DTEST
4040 IF (DTEST.GE.D(IS)) GO TO 4060
4050 CONTINUE
      IF (DTEST.EQ.72) GO TO 4060
      IK = 24
      IL = 72
      IM = 6
      GO TO 4030
4060 HVSAVE = VSAVE*VSAVE/64.32
      TPLS2 = .15 * (HVSAVE-HV(IS))
      TRULS = 1.25 * HVSAVE
      VRULS = .4 * HVSAVE
      WRITE (6,4070) AVH,HVDUM,TRULS,
1      DSAVE,VRULS,DSAVE,D(IS),
1TPLS2
4070 FORMAT (1X*AVAILABLE HEAD =*7X,F8.2
1/1X*VELOCITY HEAD =*8X,F8.2
1/1X*TEE LOSS =*,13X,F8.2
1/1X,F3.0* INCH VALVE LOSS =*2X,F8.2
1/1X*TAPER *,F3.0* TO *,F3.0* LOSS =*,F8.2)
4998 SULOSS=HVDUM + TRULS + VRULS + TPLS2
4999 WRITE (6,1070)
1070 FORMAT (24X,*-----*)
      WRITE (6,4080) SULOSS
4080 FORMAT (1X,*TOTAL LOSS*,13X,F8.2/)
      GO TO 5000
4998 HGL(IS)=AVH
      GO TO 5001
5000 HGL(IS)=AVH-SULOSS
5001 DO 1050 I=IS,NSAV
      HGL(I+1)=HGL(I)-HF(I)
1050 CONTINUE
      J = IS-1
      DO 5030 I=IS,NSAV
      IF (GS(I).EQ.0.) GO TO 5005
      J = J+1
5005 IF (AC(I).EQ.0.0) GO TO 5040
      IF (I.EQ.IS) GO TO 5040

```

**** PROGRAM LECANS ****

```

IF (LA(I).NE.LA(IS)) GO TO 5020
IF (IDUM.EQ.1) GO TO 5008
WHGR(J) = HGR(I)
GO TO 5009
5008 WHGR(J) = HGR(I) + HV(I-1)
5009 WRITE (6,5010) STA(I),HGL(I),AC(I),DQ(I),DEL(I),HGR(I),GS(I)
5010 FORMAT (1X,F10.2,8X,F8.2,41X,20X,F9.2,6X,F6.2,F5.1,F8.2,F8.2)
GO TO 5055
5020 WRITE (6,5030) STA(I),HGL(I),(LAT(I,II),II=1,2),AC(I),GS(I)
5030 FORMAT (1X,F10.2,8X,F8.2,41X,2A10,F9.2,25X,F8.2)
HGR(I)=0.0
GO TO 5055
5040 WRITE (6,5050) STA(I),HGL(I),GS(I)
5050 FORMAT (1X,F10.2,8X,F8.2,95X,F8.2)
5055 IF (ABS(HGL(I)-HGR(I)).GT.0.1) GO TO 5058
WRITE (6,5059) UNDER1,UNDER2,UNDER1,UNDER2
5059 FORMAT (1H+,19X,R8,R6,88X,R8,R6)
5058 IF (L(I).NE.0.0) GO TO 5060
WRITE (6,5056) Q(I),SAC(I),HC(I)
5056 FORMAT (13X,F7.2,75X,F10.2,26X,F5.0)
GO TO 5075
5060 WRITE (6,5070) Q(I),D(I),V(I),HV(I),H(I),L(I),HF(I),SAC(I),HC(I)
5070 FORMAT (13X,F7.2,6X,F5.0,2F6.2,F9.6,F12.2,F7.2,24X,F10.2,26X,F5.0)
*075 WRITE (6,5076) LA(I)
*076 FORMAT (1H+,19X,I5)
5075 IF (EQ(I).EQ.0.0) GO TO 5090
WRITE (6,5080) EQ(I)
5080 FORMAT (1H+,3HEQ=,F9.2)
5090 CONTINUE
NL=NSAV+1
IF (DEL(NL).EQ.0.0) GO TO 6000
WRITE (6,5010) STA(NL),HGL(NL),AC(NL),DQ(NL),DEL(NL),HGR(NL),GS(NL)
GO TO 5020
6000 WRITE (6,6010) STA(NL),HGL(NL),AC(NL),HGR(NL),GS(NL)
6010 FORMAT (1X,F10.2,8X,F8.2,41X,20X,F9.2,17X,2F8.2)
6020 IF (ABS(HGL(NL)-HGR(NL)).GT.0.1) GO TO 9999
WRITE (6,5059) UNDER1,UNDER2,UNDER1,UNDER2
9999 RETURN
END
SUBROUTINE DAMOYR (TODAY)
DIMENSION MON(12),JDATE(3),TODAY(2),CKBL(6)
DATA (MON(I),I=1,12)/10H JANUARY ,10H FEBRUARY ,10H MARCH ,
1 10H APRIL ,10H MAY ,10H JUNE ,10H JULY ,
2 10H AUGUST ,10H SEPTEMBER,10H OCTOBER ,10H NOVEMBER ,
3 10H DECEMBER /
CALL DATE(DAY)
DECODE (10,75,DAY) JDATE(3),JDATE(2),JDATE(1)
J=JDATE(2)

```

**** PROGRAM LEDANS ****

```
JDATE(2)=MON(J)
JDATE(3)=JDATE(3) + 1900
DECODE (10,85,JDATE(2)) CK3L
DO 90 I=1,6
IF (CK3L(I).EQ.14) GO TO 90
80 CONTINUE
I=7
90 J=I+3
ENCODE (11,95,FMT) J
ENCODE (20,FMT,TODAY) JDATE
75 FORMAT (3(1X,'2'))
85 FORMAT (4X,6(A1))
95 FORMAT (5H(I2,A,I2,4H,I5))
RETURN
END
```

FINAL REPORT
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY										MAIN		13 APRIL 1975				
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
0.00		1100.00													1110.00	
1500.00	7.68	1093.57	18.	4.35	.29	.004285	1510.00	6.43		110.00	565.00	1.50	6.0	1090.00	1089.00	25.
2900.00	6.19	1089.68	18.	3.50	.19	.002779	1400.00	3.89	SUB 1	200.00	455.00				1078.00	50.
2900.00	3.47	1089.68								75.00	255.00	1.02	6.0	1080.00	1077.00	50.
3671.11	2.45	1086.87	12.	3.12	.15	.003655	771.11	2.82		180.00	180.00				0.00	50.
4250.00	2.45	1081.36	10.	4.49	.31	.009518	578.89	5.51	SUB 2	80.00	180.00				1071.00	75.
5665.00	1.36	1067.94	8.	3.90	.24	.009479	1415.00	13.41		100.00	100.00				0.00	75.
5850.00	1.36	1060.00	6.	6.93	.75	.042923	185.00	7.94		100.00	100.00	1.36	6.0	1060.00	1058.00	75.

PIPE CLASS DESIGN ELEVATION = 1110.00

FINAL REPORT
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY

SUB 1-A

13 APRIL 1975

PIPE CLASS DESIGN ELEVATION = 1110.00

STATION 0 HGL DIA V HW SLOPE LENGTH LOSS SUBLATERAL NAME AC SAC DQ DEL HGR NGS HC

AVAILABLE HEAD = 1086.43
 VELOCITY HEAD = .19
 TEE --- VALVE LOSS = 1.31

0.00	1084.93	10.	2.74	.12	.003554	499.57	1.78										1079.00	50.
499.57	1083.15	8.	4.29	.29	.014470	100.43	1.15										0.00	50.
600.00	1082.00																110.00	50.

FINAL REPORT
(GRAVITY PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY

SUB 2

13 APRIL 1975

PIPE CLASS DESIGN ELEVATION = 1110.00

STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL	NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
AVAILABLE HEAD = 1081.36 VELOCITY HEAD = .31 TEE -- VALVE LOSS = 1.19 -----																	
EQ=	0.00	1079.86	8.	3.12	.15	.006067	800.00	4.85									1071.00
	-250.00	1.09										80.00	1.09	6.0	1075.00	1073.00	50.
	1050.00	1075.00									80.00						

TOTAL COST OF PIPE IS \$ 59317.86

**** INPUT FILE DATA2 ****

1.5	4.5	0.	1.53	7.1	.345	.370	6.
9		2	5.551	.48			
MAIN LATERAL							
1		0.	0.	0.09	110.		
1	200.		47.	195.	100.		
2	2000.		0.	0.	98.		
SUB LATERAL A							
2	0.		0.	0.	98.		
2	1200.		80.	192.	97.		
0	2549.83		12.2	185.	90.		
2	4900.		0.	0.	86.		
SUBLATERAL B							
2	0.		0.	0.	86.		
3	1000.		0.	0.	76.		
SUB LATERAL B-1							
3	100.		0.	0.	76.		
0	2019.87		100.	161.	66.		
0	2100.		80.	141.	46.		
1	6300.		64.	151.	56.		
0	7800.		25.	157.0	62.		
8							

DYNAMIC PROGRAMMING SOLUTION
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY										MAIN LATERAL		75/04/13.				
PIPE CLASS DESIGN ELEVATION = 236.00																
WATER SURFACE IS (231.00) IN THE TANK NEAR THE PUMPING PLANT																
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	MGS	HC
0.00		231.00														
200.00	5.55	229.94	15.	4.52	.32	.005824	200.00	1.16			408.20	.64	4.0	195.00	100.00	150.
2000.00	4.91	203.35	12.	6.25	.61	.014716	1800.00	26.49	SUB LATERAL A	92.20	361.20			203.17	98.00	150.
4900.00	3.66	179.68	12.	4.66	.34	.008162	2900.00	23.67		180.00	269.00			179.16	86.00	150.
6300.00	1.21	169.17	8.	3.47	.19	.007508	1400.00	10.51	SUBLATERAL B	64.00	89.00	.87	4.0	151.00	56.00	175.
7900.00	.34	165.14	6.	1.73	.05	.002683	1500.00	4.02		25.00	25.00	.34	3.0	157.00	62.00	200.

DYNAMIC PROGRAMMING SOLUTION
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY

SUB LATERAL A

PIPE CLASS DESIGN ELEVATION = 236.00

STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	MGS	HC
0.00	1.25	201.85	6.	3.59	.20	.000058	1200.00	9.67		80.00	92.20	1.09	6.0	192.00	97.00	150.
1200.00	.17	192.18	6.	.85	.01	.000639	1349.83	.86		12.20	12.20	.17	2.0	185.00	90.00	150.
2549.83		191.32														

75/04/13.

DYNAMIC PROGRAMMING SOLUTION
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY																
SUBLATERAL B																
PIPE CLASS DESIGN ELEVATION = 236.00																
STATION	Q	HGL	DIA	V	HW	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
0.00	2.45	176.18	10.	4.49	.31	.009518	1000.00	9.52							86.00	
1000.00	1.09	168.56	9.	3.12	.15	.006067	1100.00	6.67	SUB LATERAL B-1	100.00	180.00			168.14	76.00	175.
2100.00		161.99								80.00	80.00	1.09	6.0	141.00	46.00	200.

75/04/13.

DYNAMIC PROGRAMMING SOLUTION
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY										SUB LATERAL B-1		75/04/13.				
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
100.00	1.36	167.16	10.	2.49	.10	.002936	1919.87	5.64		100.00	100.00	1.36	6.0	161.00	66.00	76.00
2019.87		161.52														175.

PIPE CLASS DESIGN ELEVATION = 236.00

FINAL REPORT
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY																
MAIN LATERAL																
PIPE CLASS DESIGN ELEVATION = 236.00																
WATER SURFACE IS (231.00) IN THE TANK NEAR THE PUMPING PLANT																
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
0.00		231.00														
200.00	5.55	229.84	15.	4.52	.32	.005824	200.00	1.16		47.00	408.20	.64	4.0	195.00	100.00	150.
1385.49	4.91	224.43	15.	4.00	.25	.004560	1185.49	5.41			361.20				0.00	150.
2000.00	4.91	215.39	12.	6.25	.61	.014716	614.51	9.04	SUB LATERAL A	92.20	361.20				98.00	150.
4900.00	3.66	191.72	12.	4.66	.34	.008162	2900.00	23.67	SUB LATERAL B	180.00	269.00				86.00	150.
5538.20	1.21	186.92	9.	3.47	.19	.007508	638.20	4.79			89.00				0.00	175.
6300.00	1.21	161.02	6.	6.16	.59	.033999	761.80	25.90		64.00	89.00	.87	4.0	151.00	56.00	200.
7800.00	.34	157.00	6.	1.73	.05	.002683	1500.00	4.02		25.00	25.00	.34	3.0	157.00	62.00	200.

13 APRIL 1975

FINAL REPORT
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY

SUB LATERAL A

PIPE CLASS DESIGN ELEVATION = 236.00

13 APRIL 1975

STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	QA	DEL	HGR	NGS	HC
0.00		213.89	8.	3.59	.20	.008058	770.29	6.21			92.20				98.00	
770.29	1.25	207.68	6.	6.39	.63	.036488	429.71	15.68		80.00	92.20	1.09	6.0	192.00	97.00	150.
1200.00	1.25	<u>192.00</u>	6.	.85	.01	.000639	1349.83	.86		12.20	12.20	.17	2.0	185.00	90.00	150.
2549.83	.17	191.14														

AVAILABLE HEAD = 215.39
 VELOCITY HEAD = .61
 TEE -- VALVE LOSS = .89

FINAL REPORT
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY																
SUBLATERAL B																
PIPE CLASS DESIGN ELEVATION = 236.00																
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	MGS	HC
0.00		190.22														86.00
1000.00	2.45	180.70	10.	4.49	.31	.009518	1000.00	9.52	SUB LATERAL B-1	100.00	180.00				76.00	175.
2100.00	1.09	150.48	6.	5.54	.43	.027471	1100.00	30.22		80.00	80.00	1.09	6.0	141.00	46.00	200.

AVAILABLE HEAD = 191.72
 VELOCITY HEAD = .34
 TEE -- VALVE LOSS = 1.16

13 APRIL 1975

FINAL REPORT
(PUMP PROBLEM)

ECONOMICAL PIPE HYDRAULIC STUDY										SUB LATERAL B-1		13 APRIL 1975				
STATION	Q	HGL	DIA	V	HV	SLOPE	LENGTH	LOSS	SUBLATERAL NAME	AC	SAC	DQ	DEL	HGR	NGS	HC
100.00																
2019.67	1.36	179.20	8.	3.90	.24	.009479	1919.87	18.20		100.00	100.00	1.36	6.0	161.00	66.00	76.00
																175.
TOTAL COST OF PIPE IS \$										75279.43						

AVAILABLE HEAD = 180.70
 VELOCITY HEAD = .31
 TEE -- VALVE LOSS = 1.19

PIPE CLASS DESIGN ELEVATION = 236.00

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